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Impact of Non-gravitational Force Model Deficiencies for Genesis Orbit and Geodetic Parameter Estimation Based on GNSS

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G42A: Precise Orbit Determination and the International GNSS Service: Essential Disciplines and Institutions for Earth Science and Applications

12 December 2024



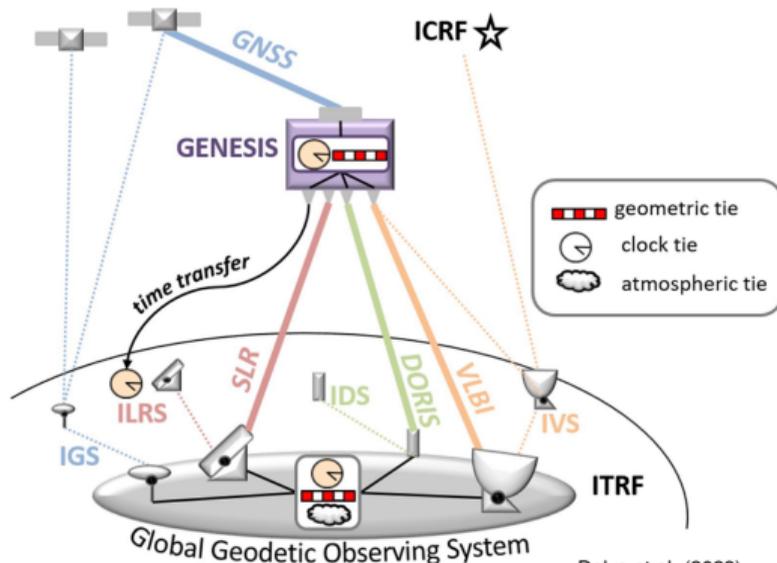
European Research Council
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Genesis mission (to be launched in 2028)



- 1 satellite with instruments for 4 space geodetic techniques
GNSS, SLR, VLBI, DORIS, accurate space ties
- Aim: Contribute to an improved International Terrestrial Reference Frame (towards GGOS goals of 1 mm accuracy / 0.1 mm/yr stability)



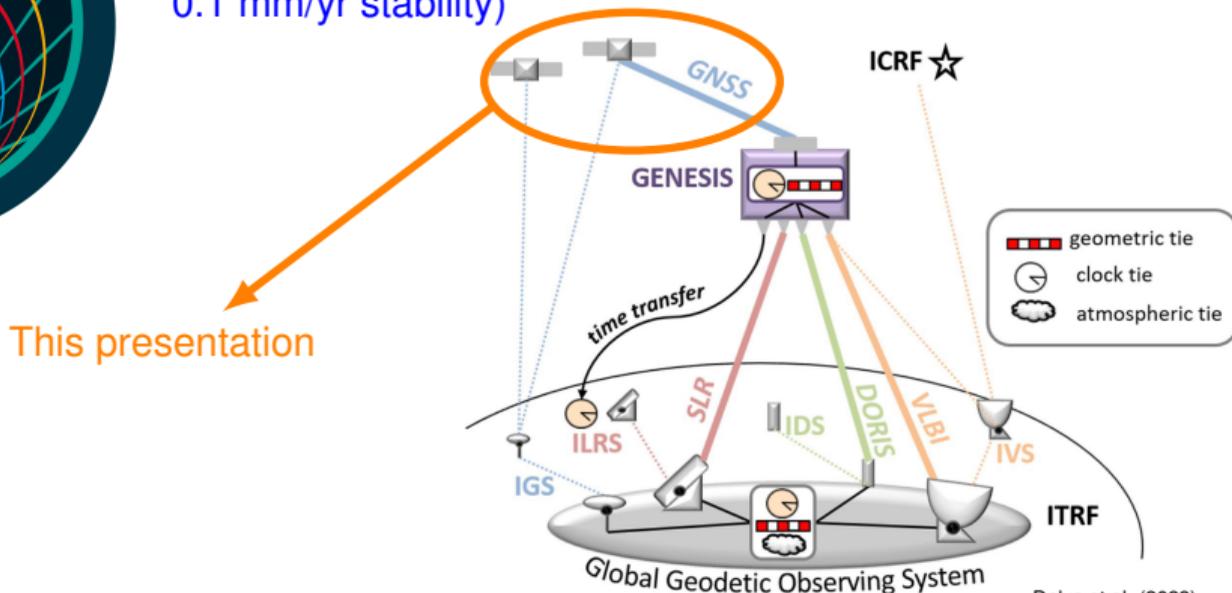
Delva et al. (2023)

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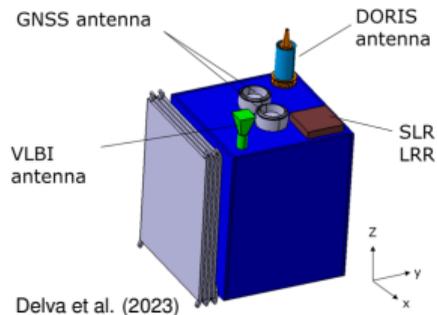
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Delva et al. (2023)

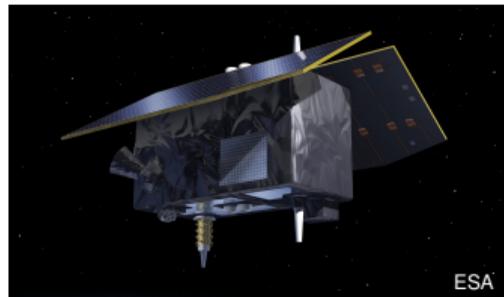
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Genesis satellite and orbit

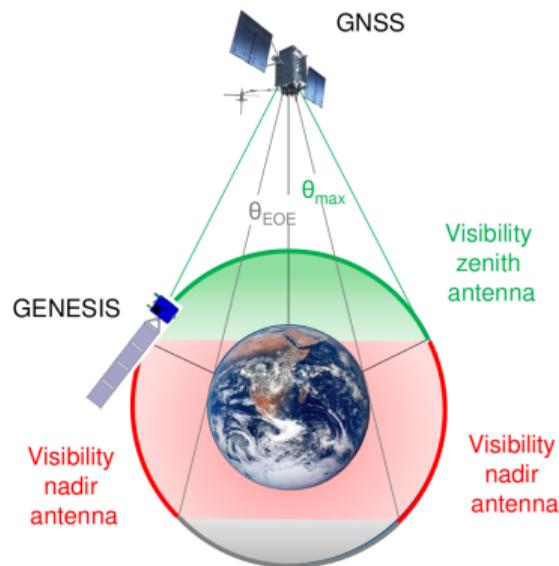


Original design (Genesis white paper)

- 6000 km altitude near-polar orbit (VLBI visibility)
- rather unfavorable GNSS tracking conditions
- zenith- and nadir-pointing GNSS antennas



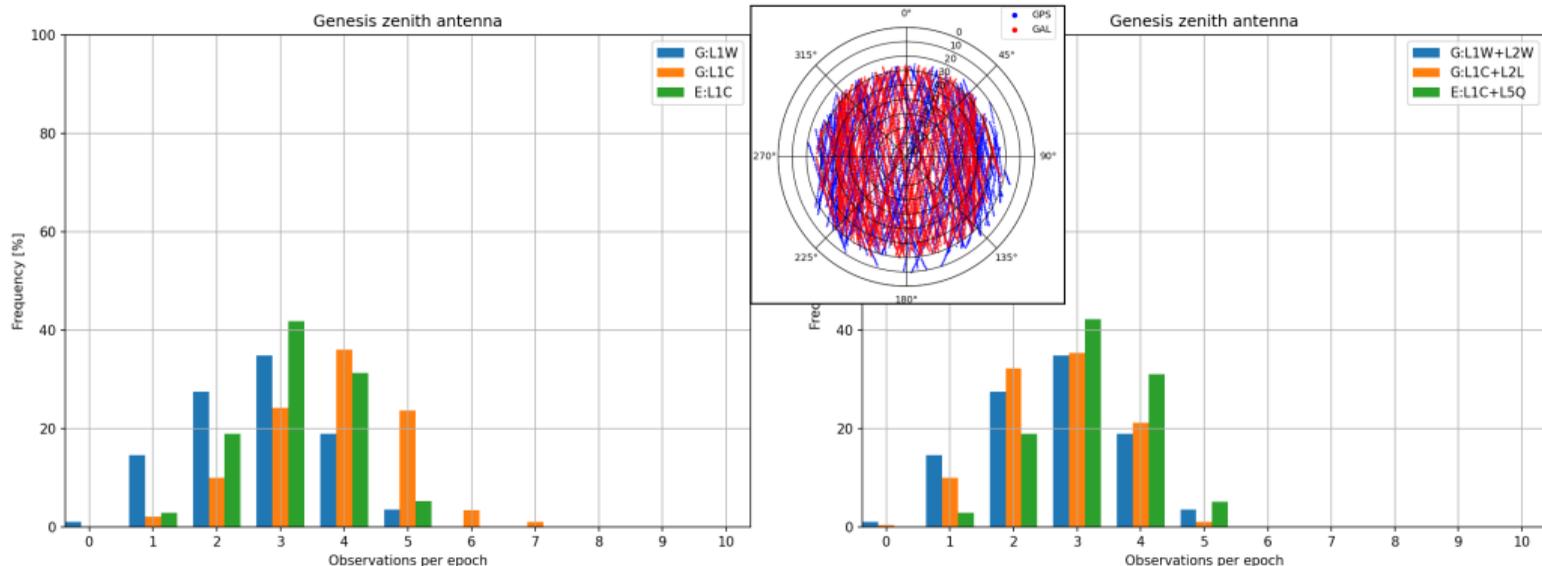
Current design (similar to Sentinel-6)



Montenbruck et al. (2023)

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Genesis GNSS tracking (zenith antenna)



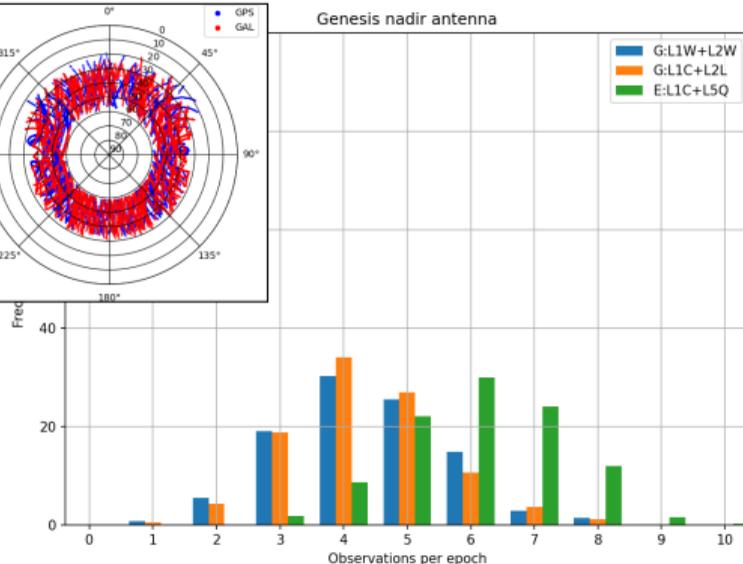
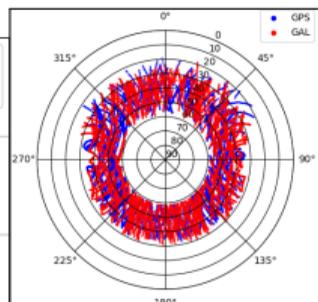
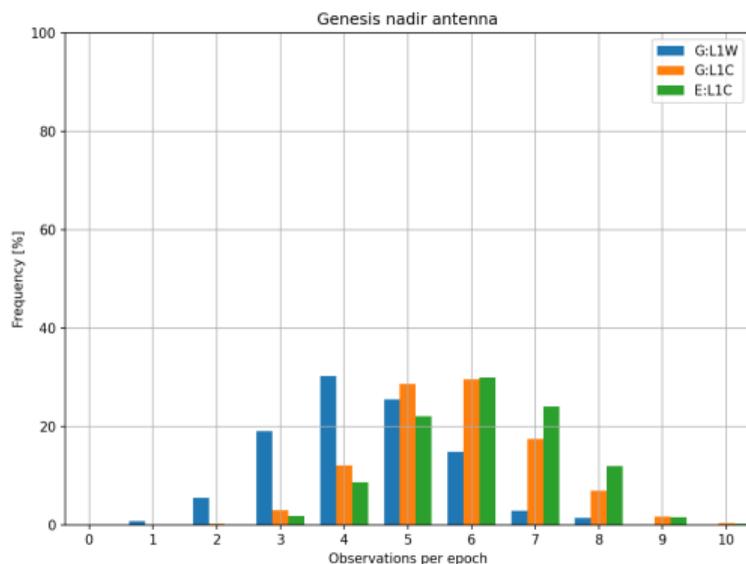
GPS	L1W:	2.7	±	1.1
GPS	L1C:	3.8	±	1.1
GAL	L1C:	3.2	±	0.9

GPS	L1W+L2W:	2.7	±	1.1
GPS	L1C+L2L:	2.7	±	1.0
GAL	L1C+L5Q:	3.2	±	0.9

Only 3-4 satellites tracked on average per epoch (worse for higher altitudes!)

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Genesis GNSS tracking (nadir antenna)



GPS	L1W:	4.4	±	1.3
GPS	L1C:	5.7	±	1.3
GAL	L1C:	6.1	±	1.3

GPS	L1W+L2W:	4.4	±	1.3
GPS	L1C+L2L:	4.3	±	1.2
GAL	L1C+L5Q:	6.1	±	1.3

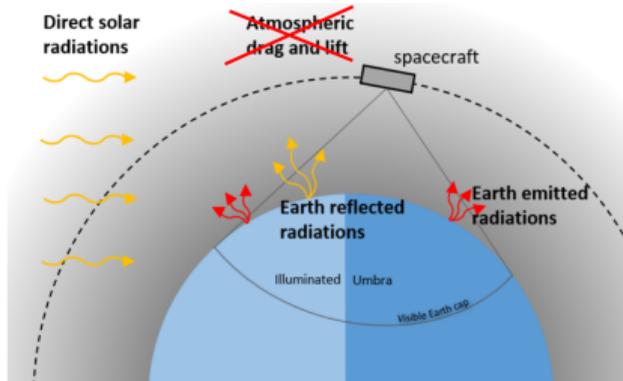
4-6 satellites tracked on average per epoch (worse for higher altitudes!)

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Non-gravitational force modeling

For Genesis, a dynamic orbit modeling is desired, as empirical orbit parameters might correlate significantly with specific geodetic parameters (to be verified)

- requires detailed explicit modeling of non-gravitational (radiation-induced) forces
- requires proper description of satellite geometry and optical surface properties

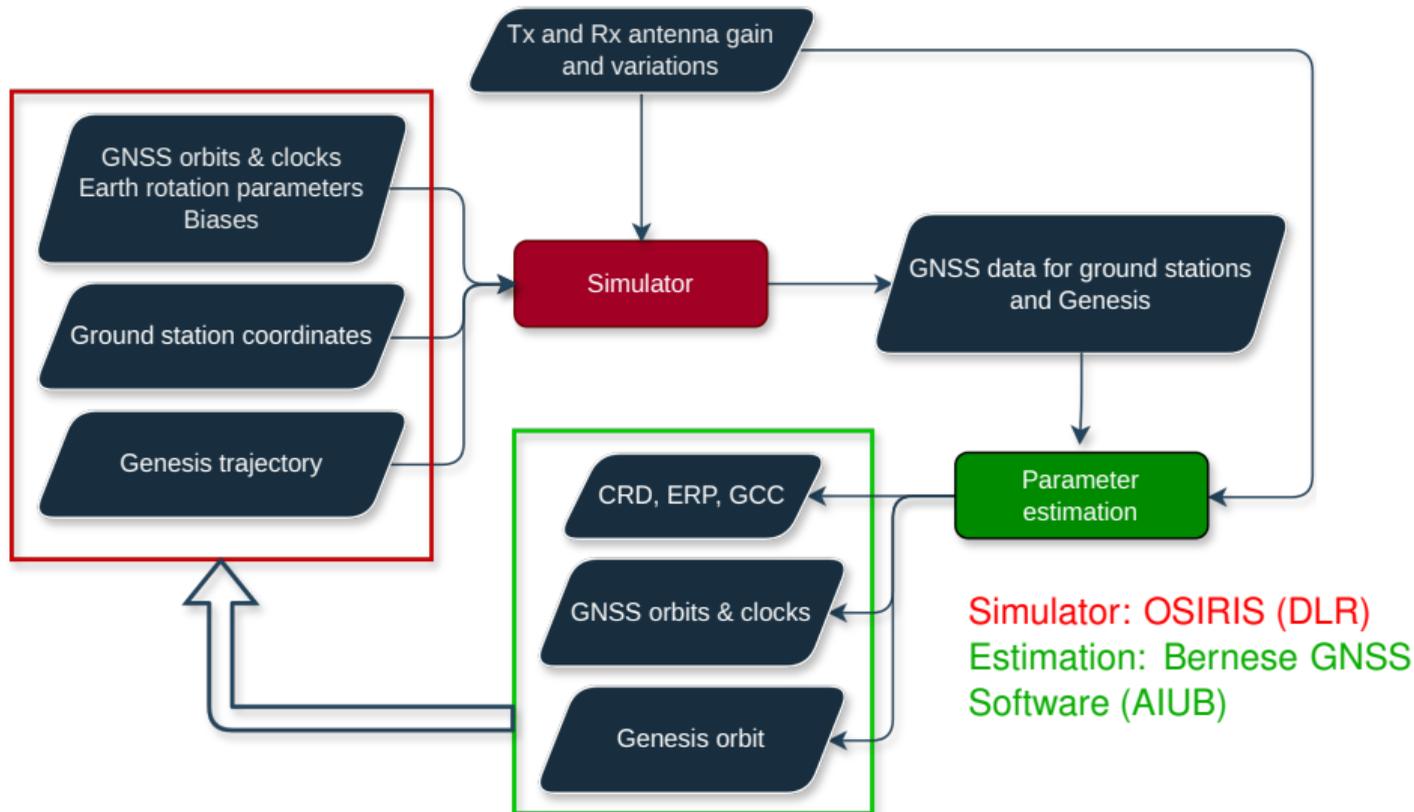


Question

How do uncertainties in the Genesis macro model affect the contribution of Genesis to global integrated GNSS solutions?

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Methods



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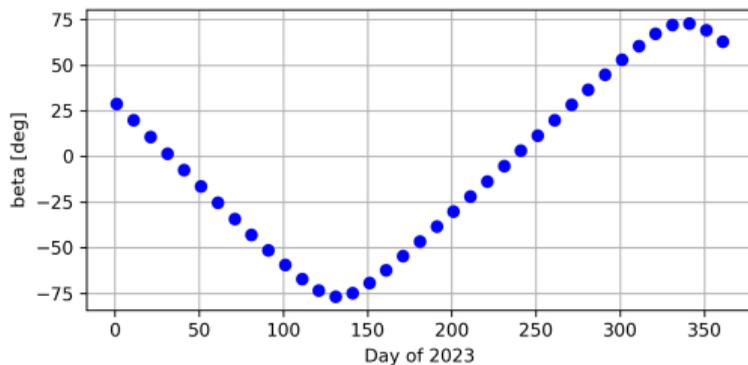
Ground stations

Selection of 100 IGS ground stations:



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Simulation



- Day 001, 011, ..., 361 of 2023 (37 days)
- Genesis orbit (5957 km, 95.5°): Dynamic orbit propagated using radiation pressure models based on 8-plate macro model for box and wing and nominal Earth pointing attitude
- GNSS products: Center for Orbit Determination in Europe (CODE) final orbits, clocks, ERPs, biases
- Station coordinates: IGS cumulative SINEX, PSD, ITRF2020 seasonal harmonics, solid Earth tides, pole tides, ocean loading
- Ionosphere: CODE GIMs (ground stations), NeQuick-G (Genesis)
- Troposphere: GPT/GMF model

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Estimation

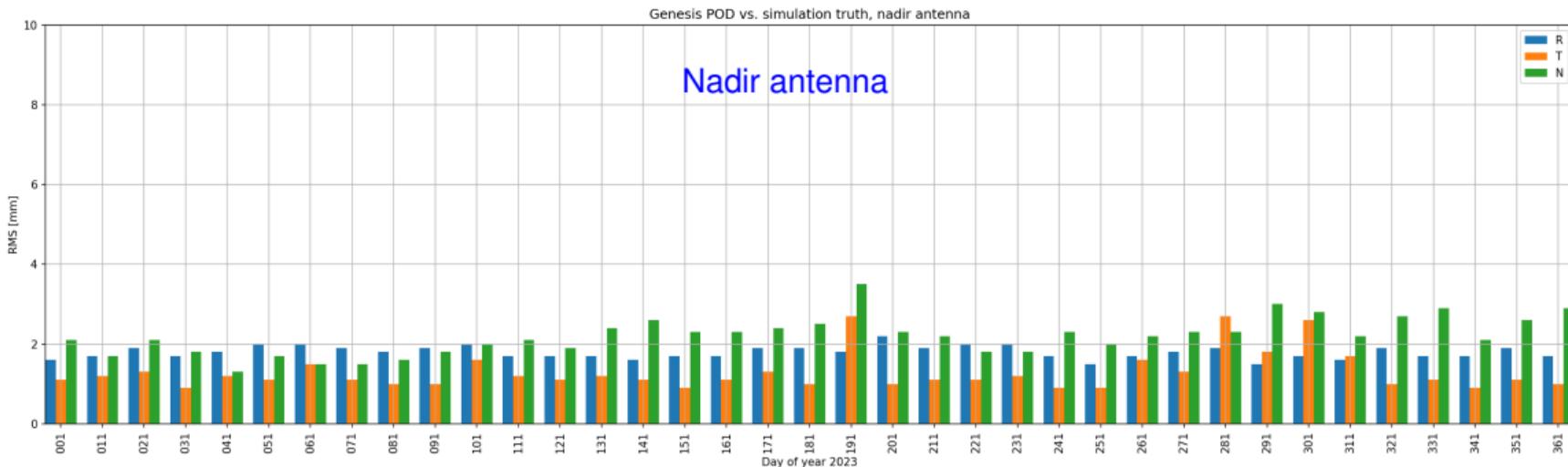
- Undifferenced GNSS data processing
- Carrier phase ambiguities fixed in PPP-AR
- Estimated parameters:
 - Station coordinates
 - Earth rotation parameters
 - Geocenter coordinates
 - Site-specific troposphere parameters
 - GNSS satellite orbits
 - GNSS satellite clocks
 - Genesis orbit (initial cond. and constrained 30' piecewise-const. acc., no scaling)
 - Station and Genesis receiver clocks
 - Observable-specific code biases
- Data sampling: 180 s (\rightarrow about 83'000 parameters/day)
- Code and phase data for ground stations, only phase data for Genesis (\rightarrow about 1'800'000 observations/day)



Procedures: Kobel et al. (2024),
DOI 10.1016/j.asr.2024.04.015

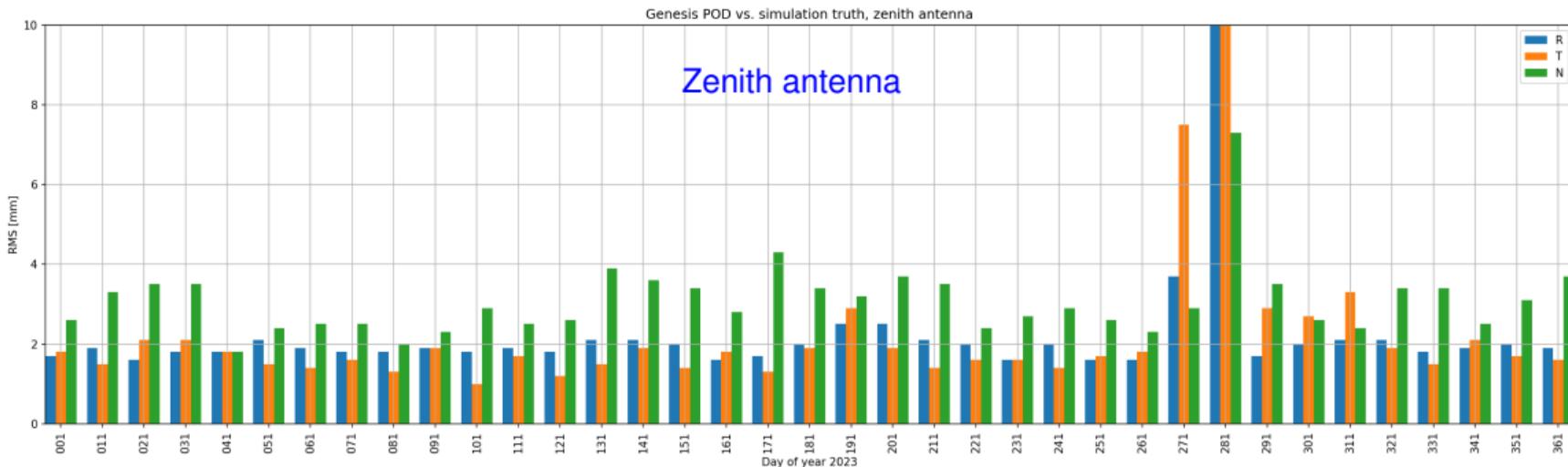
u^b “Zero” test: Genesis orbit

Genesis POD using CODE final GNSS products and the correct macro model, 30 s sampling. Differences to “true” Genesis orbit:



u^b “Zero” test: Genesis orbit

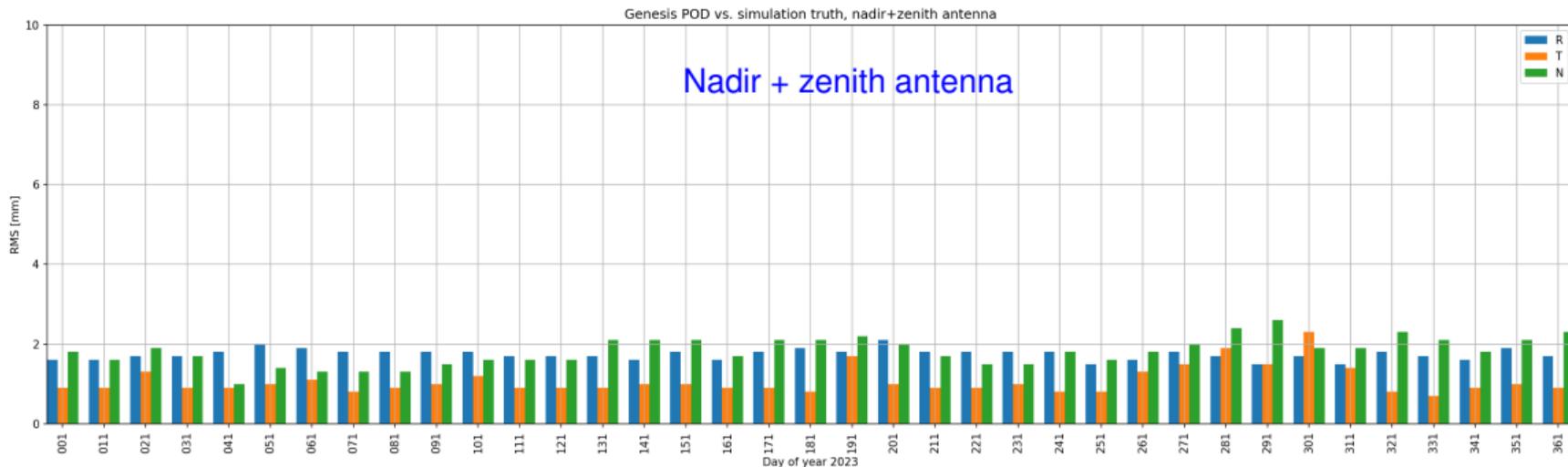
Genesis POD using CODE final GNSS products and the correct macro model, 30 s sampling. Differences to “true” Genesis orbit:



Zenith antenna-based POD more challenging

u^b “Zero” test: Genesis orbit

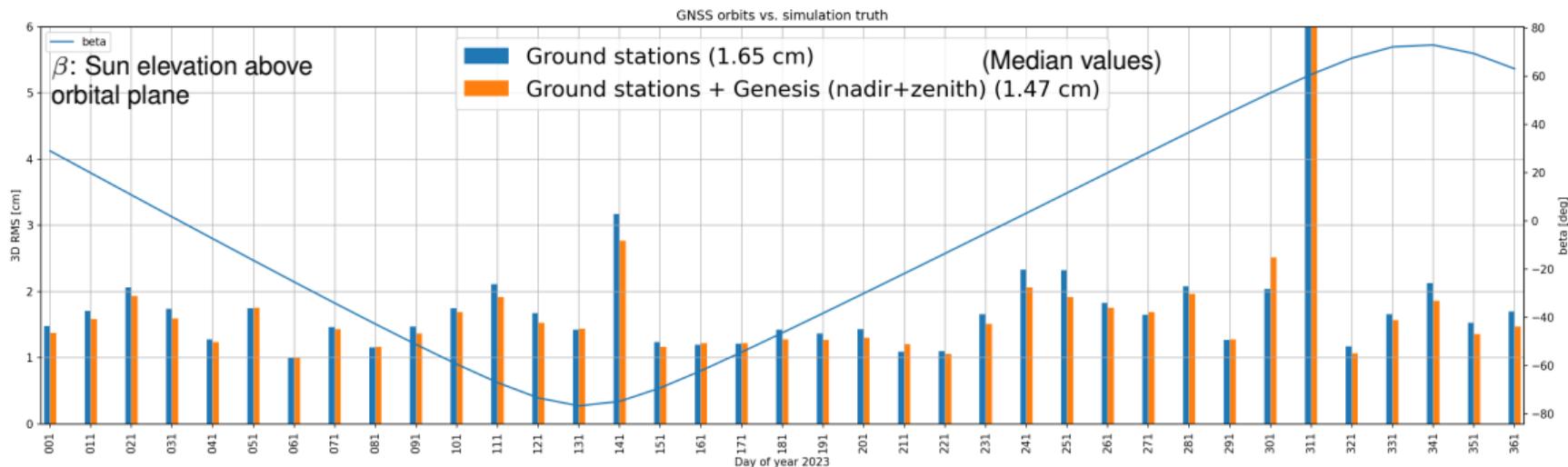
Genesis POD using CODE final GNSS products and the correct macro model, 30 s sampling. Differences to “true” Genesis orbit:



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Full parameter estimation: GNSS orbits

Estimating orbit and geodetic parameters using ground stations and Genesis data and **correct macro model**. Differences of estimated GNSS orbits compared to “true” orbits:

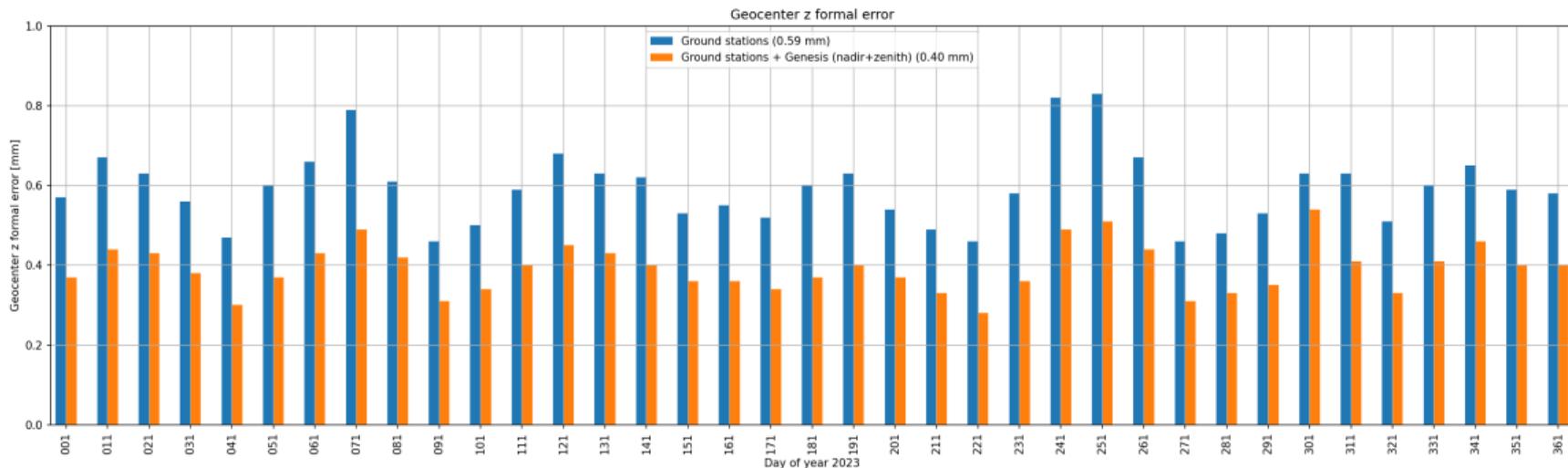


- Notice: The “true” orbits (CODE final) are 3-day orbits, while here only 1-day orbits are computed (\rightarrow slightly degraded comparison).

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Full parameter estimation: Geocenter

Formal errors of geocenter z coordinates, using **correct macro model**:



Significant reduction of formal errors due to Genesis

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Macro model error

Change visual and IR optical properties of solar panels by 0.1:

Nr	A [m ²]	n1	n2	n3	IRKspec	IRKdif	VIKspec	VIKdif	Comment
1	0.90	1.0	0.0	0.0	0.200	0.040	0.490	0.040	BODY+X (front)
2	0.90	-1.0	0.0	0.0	0.180	0.040	0.450	0.120	BODY-X (rear)
3	3.90	0.0	0.0	1.0	0.110	0.120	0.350	0.080	BODY+Z (bottom)
4	0.50	0.0	0.0	-1.0	0.220	0.010	0.620	0.030	BODY-Z (top)
5	2.20	0.0	0.61566	-0.78801	0.000	0.200	0.000	0.140	SP_+Y-Z (starboard s.p.)
6	2.20	0.0	-0.61566	-0.78801	0.000	0.200	0.000	0.140	SP_-Y-Z (portside s.p.)
7	0.30	0.0	1.0	0.0	0.130	0.120	0.430	0.140	BODY+Y (starboard)
8	0.30	0.0	-1.0	0.0	0.130	0.120	0.430	0.140	BODY-Y (portside)

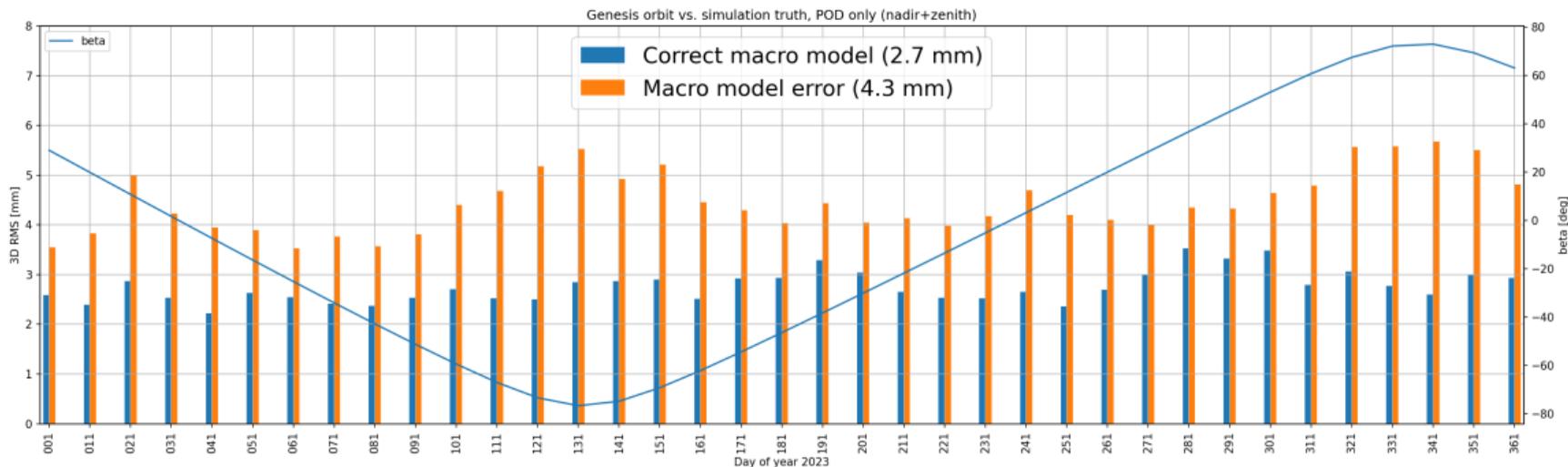
Nr	A [m ²]	n1	n2	n3	IRKspec	IRKdif	VIKspec	VIKdif	Comment
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2	0.90	-1.0	0.0	0.0	0.180	0.040	0.450	0.120	BODY-X (rear)
3	3.90	0.0	0.0	1.0	0.110	0.120	0.350	0.080	BODY+Z (bottom)
4	0.50	0.0	0.0	-1.0	0.220	0.010	0.620	0.030	BODY-Z (top)
5	2.20	0.0	0.61566	-0.78801	0.100	0.300	0.100	0.240	SP_+Y-Z (starboard s.p.)
6	2.20	0.0	-0.61566	-0.78801	0.100	0.300	0.100	0.240	SP_-Y-Z (portside s.p.)
7	0.30	0.0	1.0	0.0	0.130	0.120	0.430	0.140	BODY+Y (starboard)
8	0.30	0.0	-1.0	0.0	0.130	0.120	0.430	0.140	BODY-Y (portside)

For simulation

For reconstruction

u^b Impact on Genesis orbit

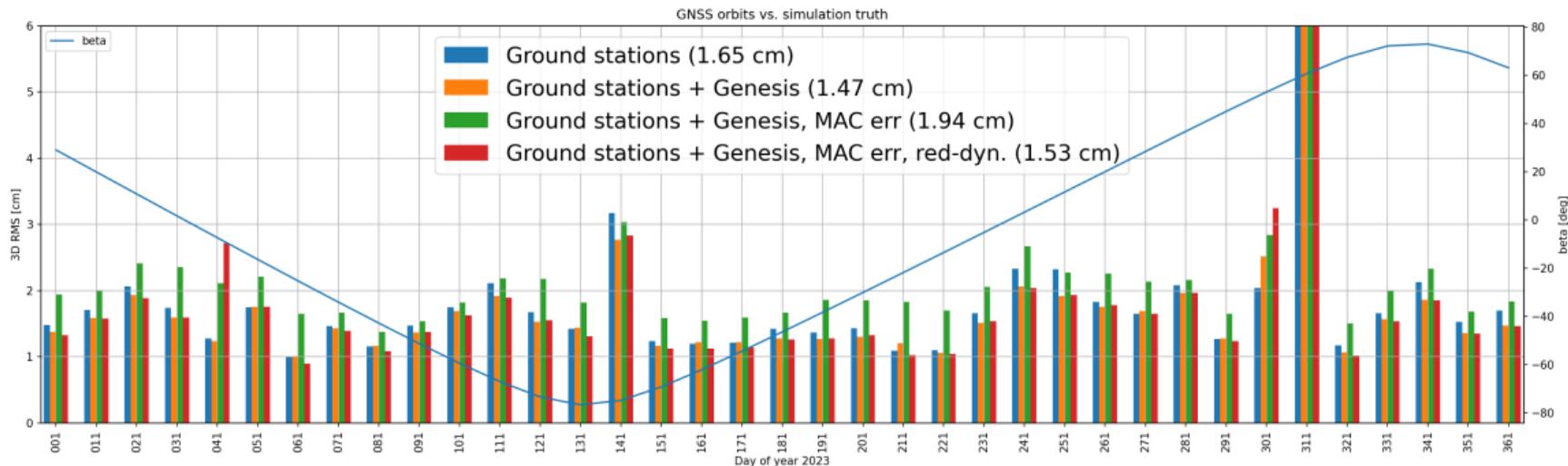
Genesis orbit differences from a dynamic POD-only solution:



β -dependent degradation of Genesis orbit

u^b Impact on GNSS orbits

Differences of estimated GNSS orbits compared to “true” orbits:

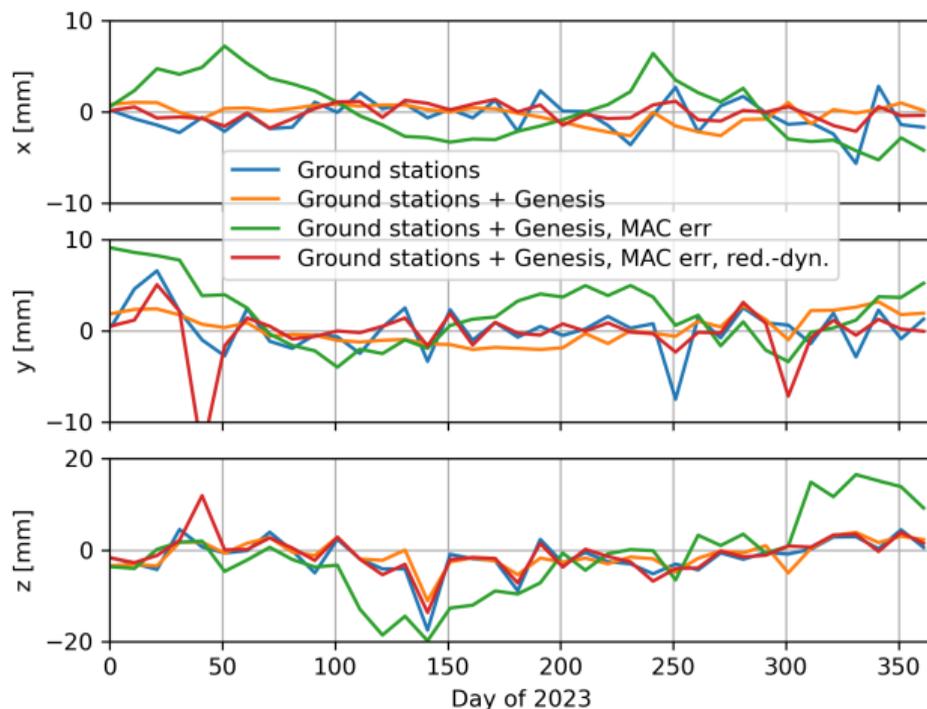


- Macro model error leads to visible degradation of GNSS orbits
- Relaxing constraints for Genesis piece-wise constant accelerations (**red.-dyn. solution**) allows to compensate to a large extent for the macro model error

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Impact on geocenter coordinates

Estimated geocenter coordinates:



Median \pm MAD:

-0.6 ± 1.1 mm

$+0.1 \pm 0.6$ mm

$+0.0 \pm 2.9$ mm

-0.1 ± 0.7 mm

$+0.4 \pm 1.4$ mm

-0.3 ± 1.2 mm

$+1.5 \pm 2.5$ mm

$+0.0 \pm 0.9$ mm

-0.9 ± 1.9 mm

-1.5 ± 1.6 mm

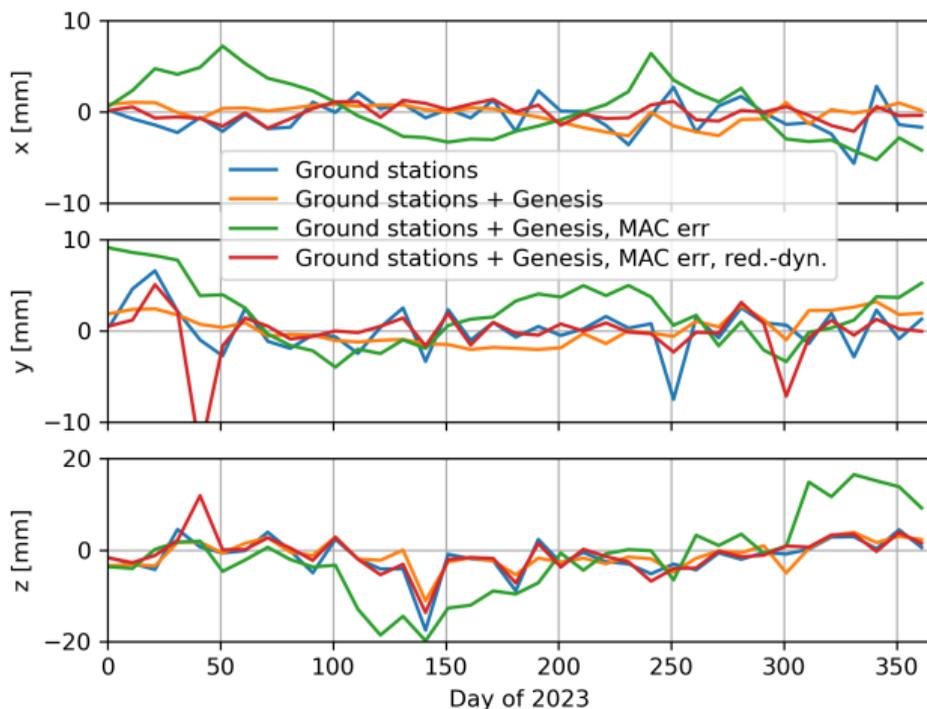
-0.8 ± 3.9 mm

-1.2 ± 1.8 mm

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Impact on geocenter coordinates

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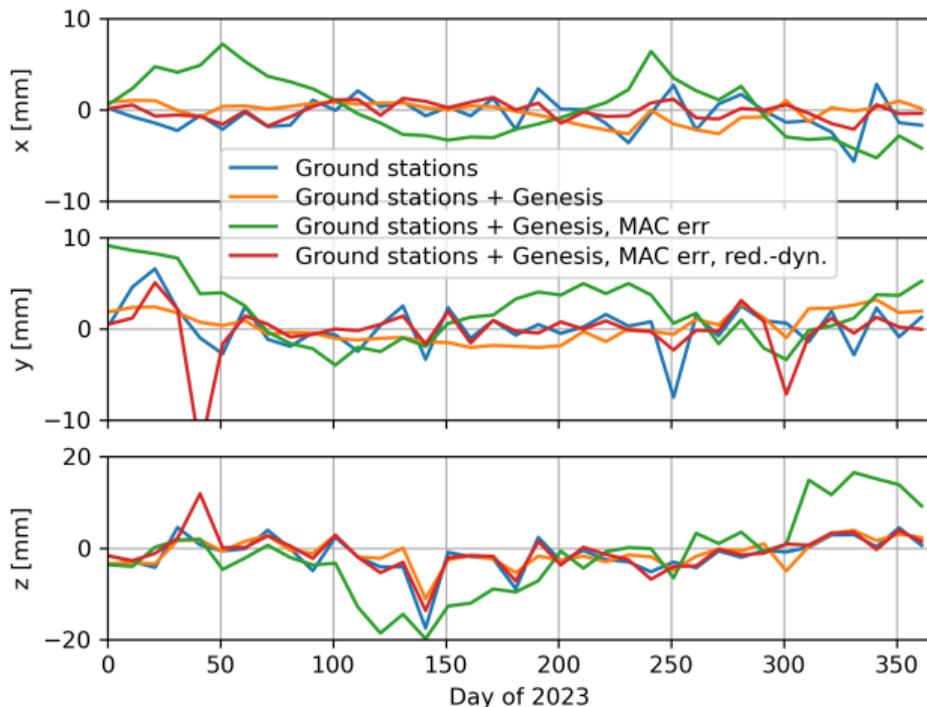
-1.2 ± 1.8 mm

Macro model error
leads to degradation

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Impact on geocenter coordinates

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-1.5 ± 1.6 mm

-0.8 ± 3.9 mm

-1.2 ± 1.8 mm

Reduced-dynamic Genesis orbit helps

Conclusions

- The GNSS tracking of Genesis is less straightforward than for LEOs (especially zenith antenna).
- Established a simulation framework to study impact of systematic non-gravitational force modeling (and other) errors on orbit and global solutions.
- In case of a dynamic Genesis orbit modelling, an error of 0.1 in Genesis solar panel optical properties has a visible impact on Genesis and GNSS orbits and geocenter coordinates.
- Relaxing constraints of Genesis piecewise-constant accelerations (more reduced-dynamic orbit) mitigates influence of macro model error without a large degradation of orbits and geocenter
- Further geodetic parameters and macro model errors to be studied...

Thank you!

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