

Issues of GOCE SSTI processing

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Introduction

ESA's first Earth Explorer Core Mission GOCE is equipped with a 12-channel dual-frequency Lagrange GPS receiver. The GPS data are primarily used for precise orbit determination of the satellite and the derivation of the long wavelength part of the Earth's gravity field. The Precise Science Orbits (PSO) derived from the almost continuous 1 Hz GPS data series meet the mission accuracy requirement of 2 cm.

The GOCE PSOs are, however, of slightly reduced quality over the polar regions. This is particularly important and evident for kinematic positions, where an inferior quality directly maps into subsequent gravity field solutions. The root-cause for the degradation is not yet fully understood, a direct correlation with more frequent L2 tracking losses occurring near the geomagnetic poles could not yet be clearly demonstrated.

Possible interactors are the observation geometry, which is slightly worse near the poles, and the ionosphere that is coupled with solar activity and the magnetic field of the Earth. We show correlations with these interactors and present the state of findings.

Method of analysis: To assess the orbit accuracy, the GPS phase residuals of the routinely processed reduced dynamic PSO are studied. The RMS of the residuals is related to the number of available observations, their quality and geometry. Gaps occur due to signal losses (either L1 or L2) and due to data screening because of bad signal to noise ratio or too little observations per epoch. To separate antenna specific issues from atmospheric influences, the RMS as well as the number of observations and the number of gaps is plotted in different coordinate systems (earth fixed (φ/λ), antenna fixed (Az/Ele) or related to the direction of the sun (u/β)).

U/ β -plane (fig. 1): The u/β -plane visualizes the directional influence of the sun. The β -angle varies slowly with time between 59° and 90°, shown is the period from day 62 to day 171, 2010. The distribution of observations is very homogeneous (more observations only when β is turning). Gaps occur mainly near the poles ($u \sim 90^\circ, 270^\circ$), the RMS is degraded near the poles and at the magnetic equator. There is a seasonal influence visible near the south pole in the RMS-plot. The increase in gaps around $\beta = 67.2^\circ$ corresponds to a degradation after day 121, probably due to a magnetic storm around this date.

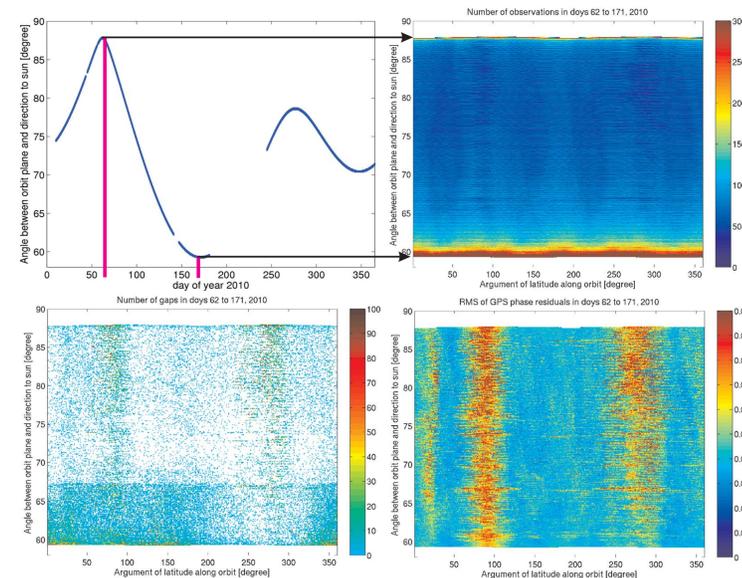


Fig. 1a-d: β -angle in 2010, observations, gaps and orbit quality in u/β -plane.

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L2-Losses in the skyplot:

The skyplot is an antenna fixed system. The azimuth of the observation is counted clockwise (flight direction to the top of the plot), the elevation of the observations is 0° at the outer border, 90° in the center of the plot. L2-losses occur mainly at low elevations in cross track direction. There exist sharply distinguished maxima around $Az=270^\circ$, some less striking features between $Az=80^\circ$ and 125° and close to $Az=180^\circ$. These accumulations of gaps in a few places suggest "blind spots" of the GPS receiver antenna. In fig. 3 it is shown, that some of them may also be due to correlations with the ionosphere.

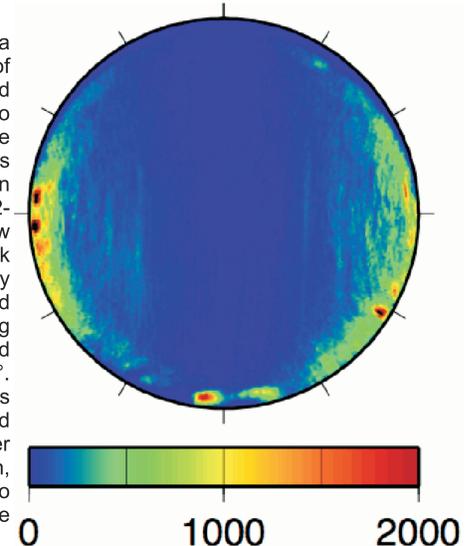
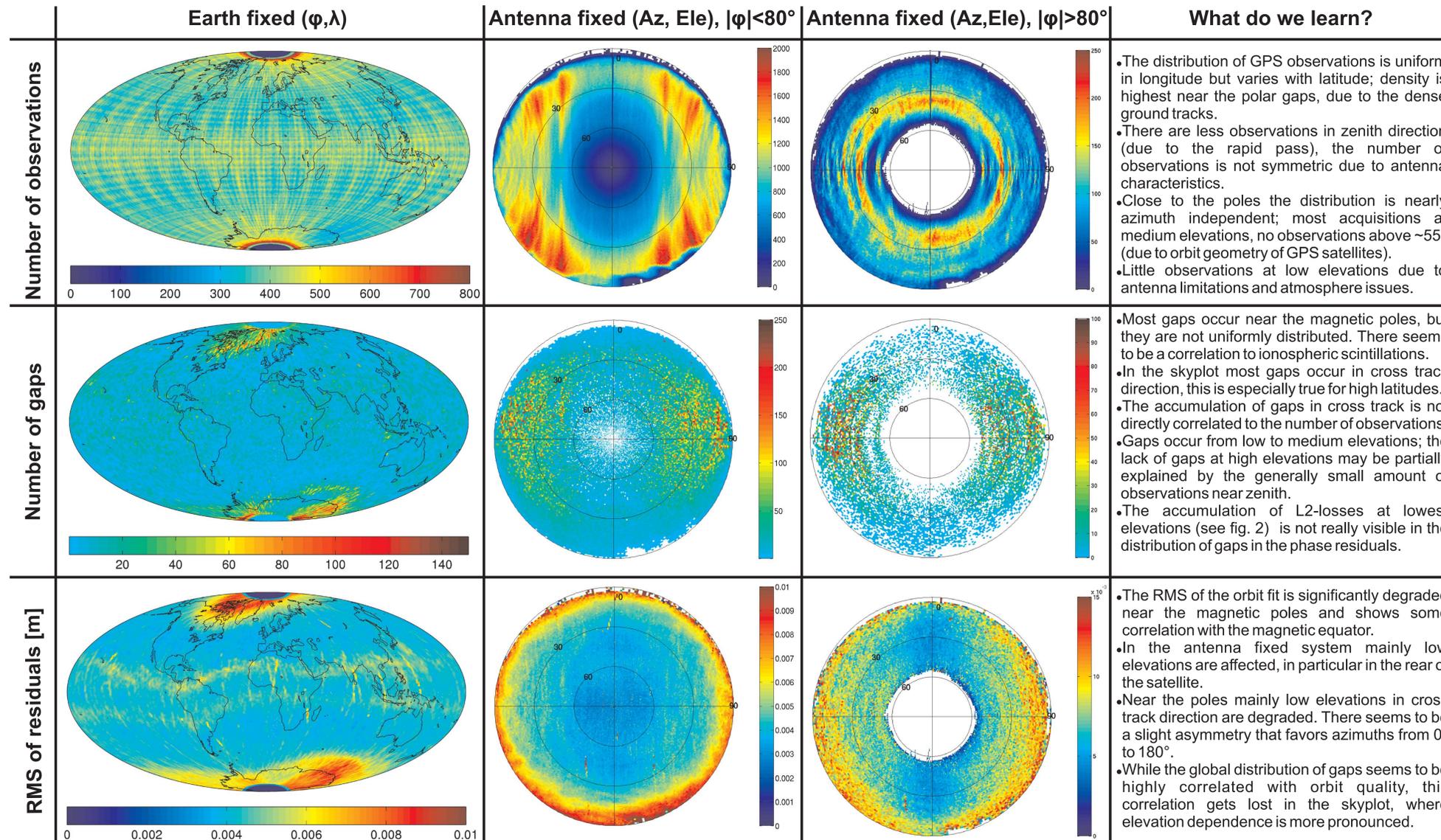


Fig. 2: L2-losses in the middle of a pass, extracted directly from the RINEX observation files.



Where is the sun: GOCE follows a dusk-dawn orbit. As a consequence, the sun is relative to the GPS antenna always at a low (or negative) elevation to the left. More precisely, the sun's track on the skyplot is a circle around $Az=270^\circ$ and $Ele=0^\circ$ with a radius corresponding roughly to $90^\circ - \beta$. In fig. 3a the RMS of the residuals near day 62 to 171, 2010 is mapped to the corresponding location of the sun. In fig. 3b the number of observations at $|\varphi| > 80^\circ$ are mapped in the same way. Figures 3c and 3d show the results for day 278 to 347. As already shown, the orbit quality is worse near the poles. It may be noted, that most L2-losses (fig. 2) occur at low elevations in the direction of the sun, when GOCE passes a pole. This points again to trouble with the ionosphere.

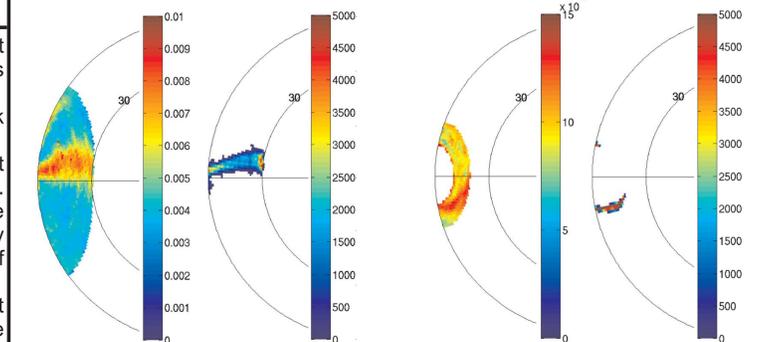


Fig. 3a-d: RMS [m] and number of observations near pole during day 62 to 171 (left) and day 278 to 347 (right), mapped to position of sun.

Conclusion:

All analyses point to an influence of the ionosphere on the signal reception of the GPS antenna onboard GOCE. The ionosphere interacts with the magnetosphere and is heated by the sun. Signal reception is degraded at low elevations (long travel time through ionosphere) near magnetic equator and poles in the direction of the sun (where the ionosphere is heated most). L2-losses to the right and the rear of the satellite may be antenna specific (to be verified).

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