Updated phase center corrections for satellite and receiver antennas

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igs05.atx vs. igs08.atx -

| | igs05.atx | igs08.atx | |
|-------------------------------|---|---|--|
| GPS satellite antennas | 11 years of data, 2 ACs | 16 years of data, 4 ACs | |
| | solutions aligned to IGb00 (based on relative phase center corr.) | solutions aligned to IGS08, i.e., full consistency with reference frame | |
| | trend-correction due to error in mean vertical velocity of IGb00 | no common z-offset trend | |
| | radome calibrations not considered | available radome calibrations applied | |
| | block mean values for satellites launched since 2006 | satellite-specific estimates for 8 latest satellites | |
| GLONASS sat. ant. | 15 months of data, 1 AC | 7/2.5 years of data, 2 ACs | |
| Receiver antennas | robot calibrations for about 60% of the IGS stations | robot calibrations for about 70% of the IGS stations | |
| | GPS-specific corrections only | GPS- and GLONASS-specific corrections | |





repro1 processing strategy -

| | CODE | GFZ | MIT | NRCan |
|---------------------|-----------------------------|----------------------------|--------------------------------|----------------------|
| Elevation cut-off | 3° | 7° | 10° | 10° |
| Weighting | 1/cos ² (z) | 1/2sin(e) for e < 30° | $a^2 + (b^2/\sin^2(e))$ | none |
| Meteo data | GPT | GPT | GPT | ECMWF 6 h grids |
| Zenith delay | Saastamoinen dry | Saastamoinen dry + wet | Saastamoinen dry + wet | ECMWF dry + wet |
| Mapping function | GMF dry | GMF dry + wet | GMF dry + wet | NMF dry + wet |
| Zenith parameters | 2 h continuous with GMF wet | 1 h constants with GMF wet | 2 h continuous with GMF wet | 5 min stochastic ZTD |
| Gradient parameters | 24 h NS + EW continuous | 24 h NS + EW constants | NS + EW vary linearly | 5 min stochastic |

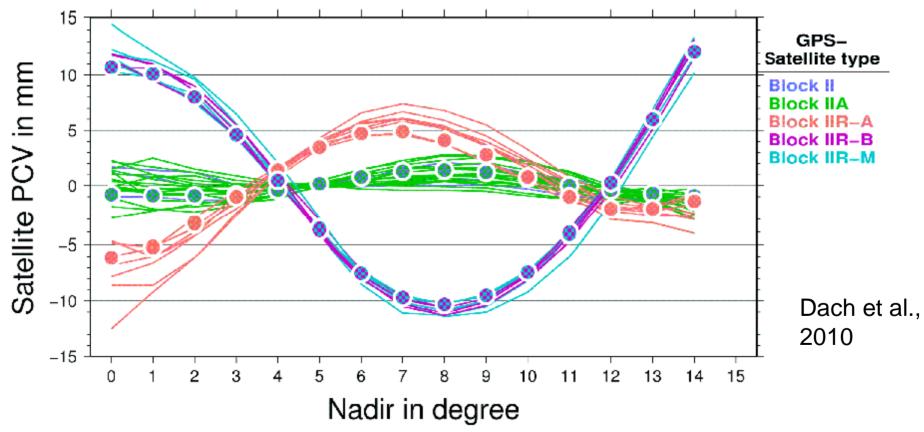
Griffiths et al., 2009





GPS satellite antenna PCVs

- SINEX format does not allow for antenna PCVs so far
- Impossible to derive PCVs consistent with z-offsets from SINEX files, i.e., PCVs from igs05.atx will be kept
- PCVs from current CODE solution still show good agreement

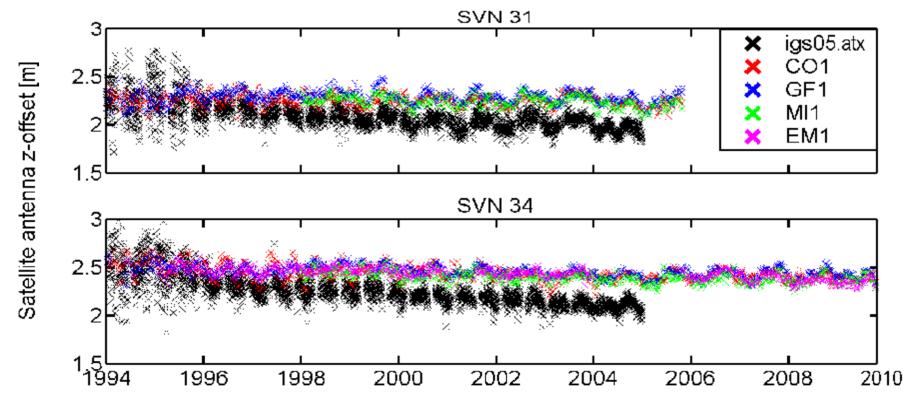






GPS satellite antenna PCOs

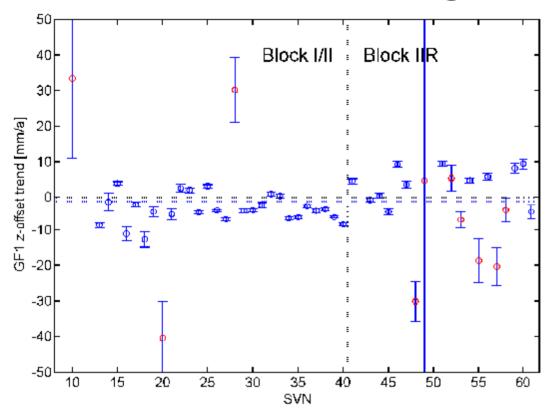
- Different scatter: daily (igs05.atx) vs. weekly estimates (repro1)
- Trend due to error in mean vertical velocity of IGb00 has more or less disappeared
- Certain satellites fixed in MIT and NRCan solutions (e.g., SVN 31)
- Preliminary results with ITRF2008P kept fixed







Remaining z-offset trends



| Trends [mm/a] | igs05.atx (Schmid et al., 2007) | igs08.atx |
|------------------|---------------------------------------|-----------|
| CODE/ TUM | -24.8 | -4.9 |
| GFZ | -22.0 | -1.3 |
| MIT | | -1.9 |
| NRCan | | -3.9 |

Altamimi et al. (AGU 2009):

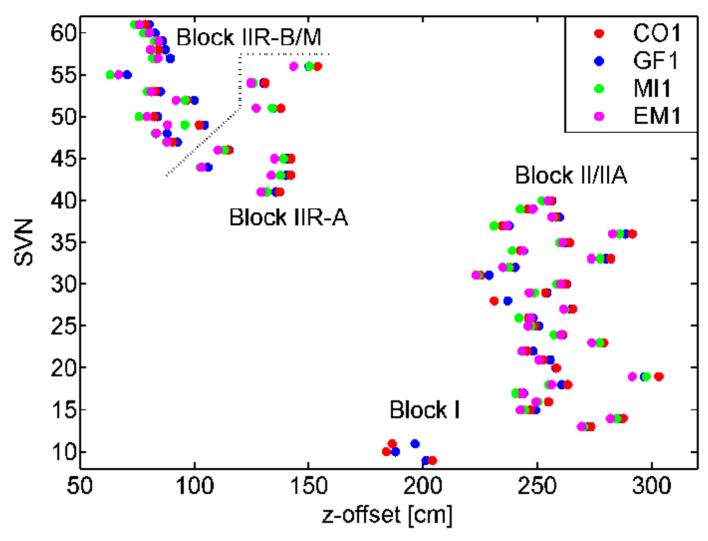
Scale rate agreement between VLBI and SLR: 0.06 ppb/a

- \rightarrow ± 0.03 ppb/a correspond to a z-offset trend of about ± 4 mm/a
- → GPS tends to support the SLR scale rate





Absolute GPS z-offsets by SVN

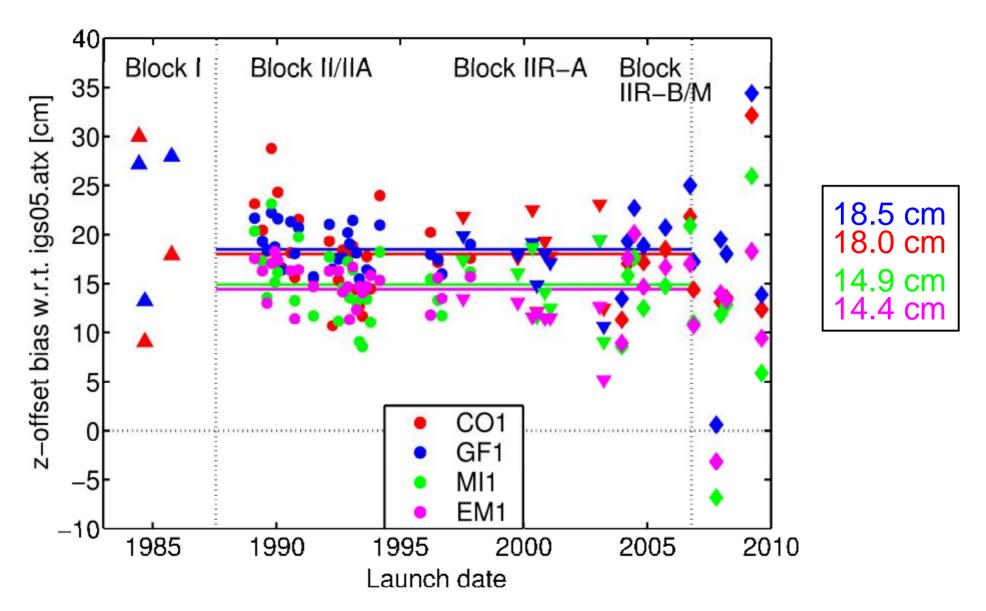


Differences between ACs are much smaller than satellite-to-satellite differences within each block





z-offset bias w.r.t. igs05.atx (I)







z-offset bias w.r.t. igs05.atx (II)

• Bias w.r.t. igs05.atx:

§ CODE: $18.0 \text{ cm} \pm 3.9 \text{ cm}$

§ GFZ: $18.5 \text{ cm} \pm 2.7 \text{ cm}$

§ MIT: $14.9 \text{ cm} \pm 3.5 \text{ cm}$

§ NRCan: 14.4 cm ± 2.8 cm

Bias between GFZ and CODE/TUM:

§ igs05.atx (Schmid et al., 2007): about 4 cm

§ igs08.atx: **0.5 cm**

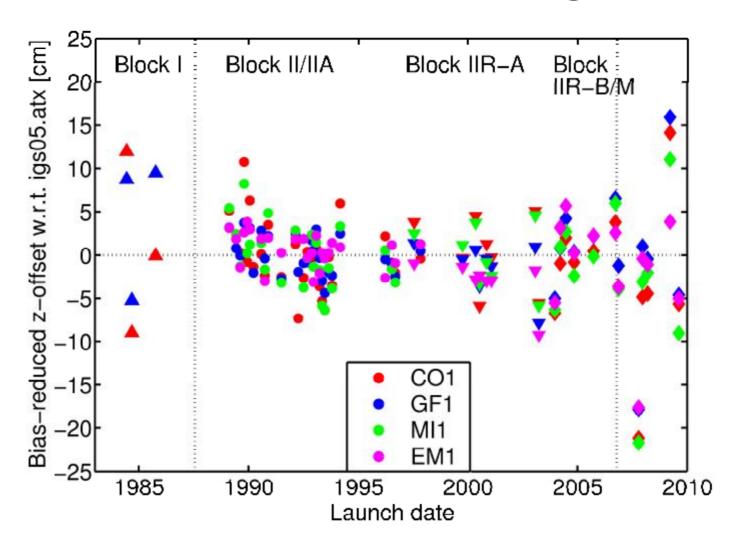
Altamimi et al. (2010):
 Scale difference between ITRF2005 and ITRF2008P: -1.13 ppb

- Zhu et al. (2003): -1.13 ppb correspond to about +14.5 cm
- Part of the bias between CODE/GFZ and MIT/NRCan possibly due to certain fixed satellite offsets in the MIT/NRCan solutions





Bias-reduced z-offsets w.r.t. igs05.atx

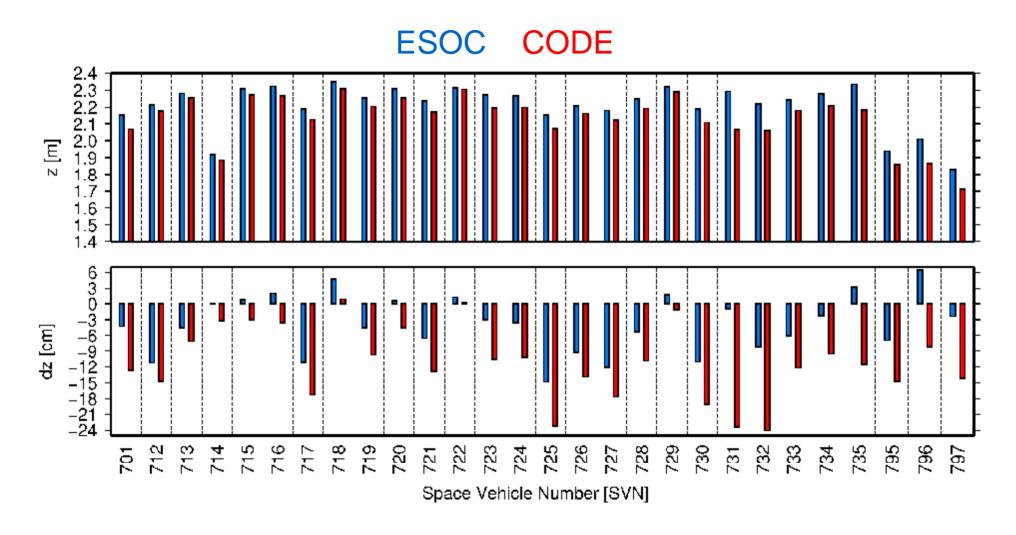


- → igs08.atx and igs05.atx agree at the ±5 cm level
- → Preliminary values for Block IIR-B/M were not too bad





GLONASS satellite antenna corrections



Mean bias between ESOC and CODE: 7.3 cm





Receiver antenna calibrations

GPS:

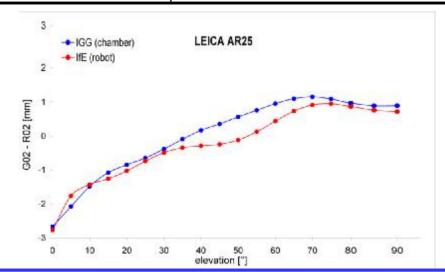
- 15 additional robot calibrations (e.g., for TPSCR3_GGD)
- update for 61 existing robot calibrations

Statistics for stations in the IGS network (December 2009):

| Model | absolute calibration | converted field calibration | uncalibrated antenna/ radome combination |
|-----------|----------------------|-----------------------------|---|
| igs05.atx | 62% | 18% | 20% |
| igs08.atx | 69% | 11% | 20% |

GLONASS:

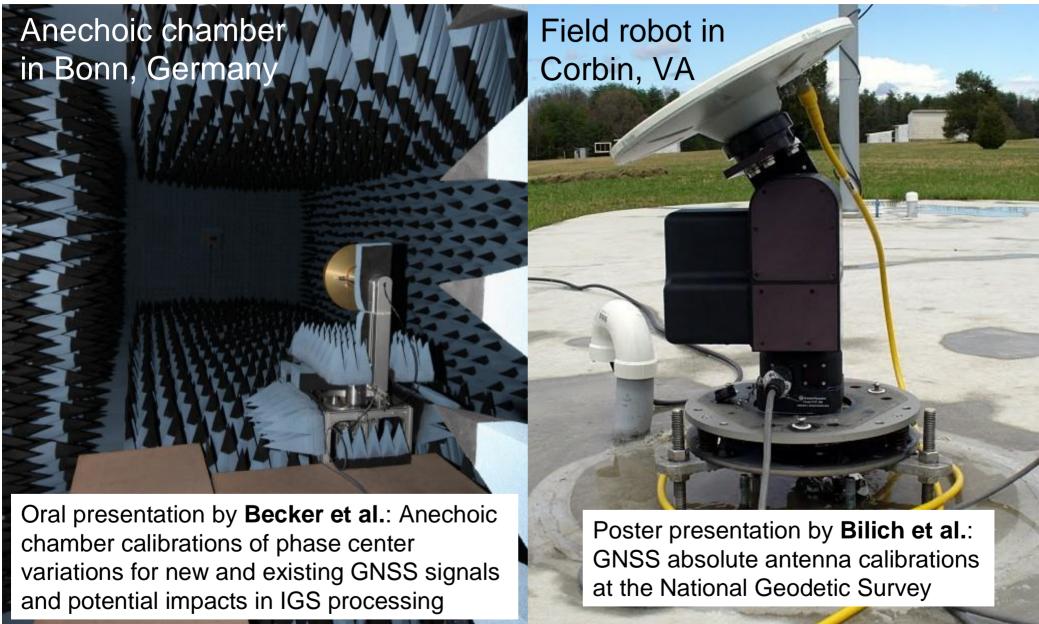
- GLONASS-specific calibrations not considered so far
- available for about 60% of the GPS/GLONASS stations







New absolute calibration institutions







Antenna format updates

ANTEX:

- Allow for frequency-specific GLONASS calibrations?
- How to store receiver-dependent carrier-to-noise patterns CN0?
- Necessary to store near- and/or far-field effects?
- Header of a single antenna type does not allow for calibrations from different institutions/antenna samples/etc.

SINEX:

- Add GLONASS-specific receiver antenna corrections (additional SITE/GLO_PHASE_CENTER block)
- Allow for satellite antenna phase center variations?

antenna.gra:

Define antenna northing





Conclusions

- Consistency between ITRF2008/IGS08 and igs08.atx will be far better than between IGS05 and igs05.atx
- Remaining GPS satellite antenna z-offset trends are within the uncertainty of the ITRF2008 scale rate; GPS closer to SLR
- z-offset bias w.r.t. igs05.atx can mainly be explained by scale change of about 1.1 ppb
- z-offset biases between ACs are small and probably caused by single fixed offset values in certain AC solutions
- Highly improved GLONASS satellite antenna corrections (more satellites/tracking stations/analysis centers)
- Uncalibrated equipment is still a big problem
- Reference Frame Working Group has to check the impact of updated receiver antenna calibrations on IGS08





