

Near-real Time GPS Clock Generation at CODE

Heike Bock
Astronomical Institute
University of Bern
Switzerland

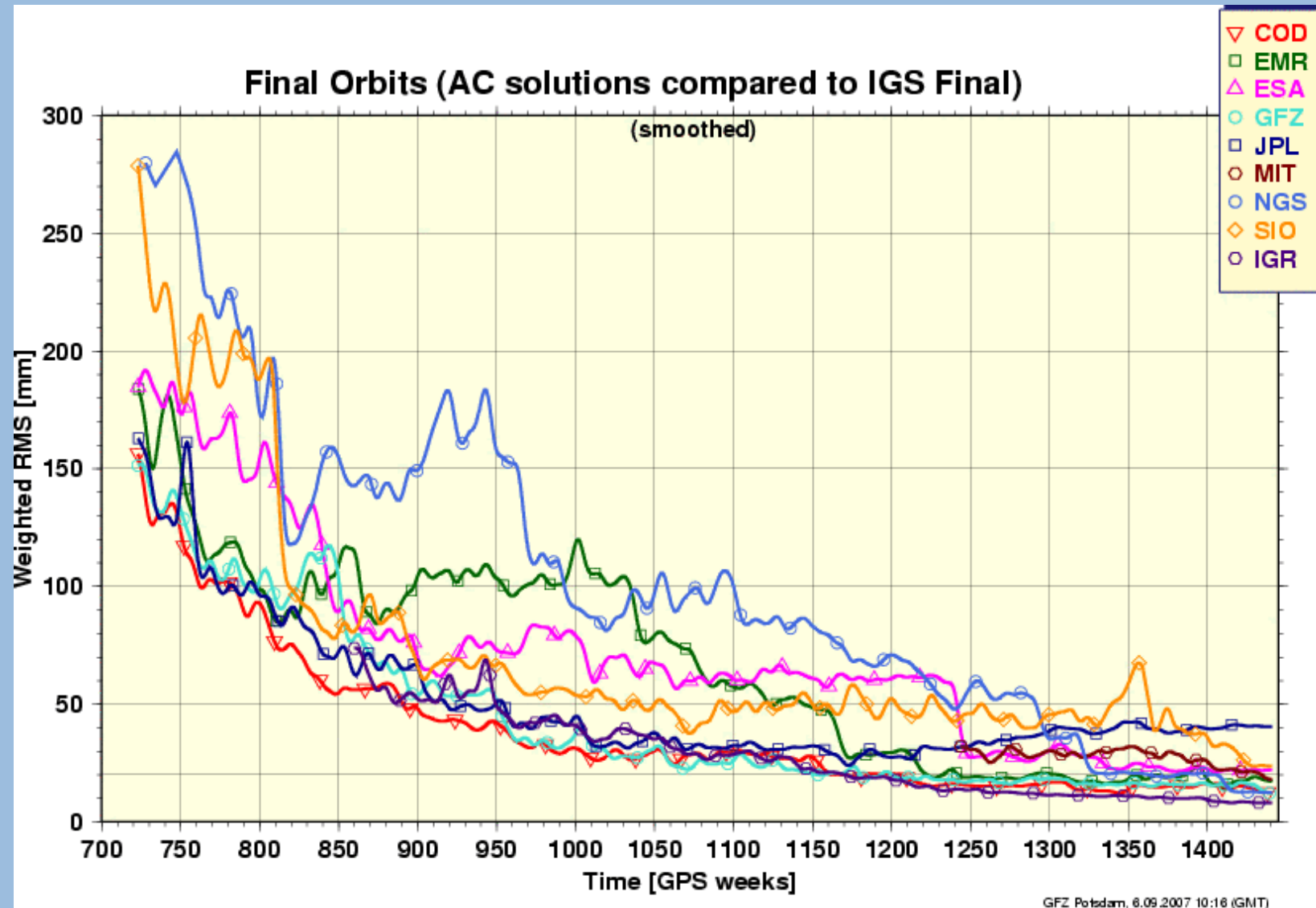
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- > Concept for the generation of NRT GPS clock corrections
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IGS / CODE / AIUB

- > The Center for Orbit Determination in Europe (CODE) is one of the IGS analysis centers contributing to the IGS from the very beginning
- > CODE is a joint venture of
 - Astronomical Institute, University of Bern, Switzerland (host)
 - Bundesamt für Landestopografie swisstopo, Wabern, Switzerland, and
 - Bundesamt für Kartographie und Geodäsie, Frankfurt, Germany
- > All CODE GNSS products are generated with a processing software developed at AIUB => Bernese GPS Software (BSW)

IGS / CODE / AIUB



IGS => Products

		Accuracy	Latency	Updates	Sample Interval
Broadcast	orbits sat. clocks	~ 160 cm ~ 7 ns	real time	(every two hours)	
Ultra Rapid (predicted half)	orbits sat. clocks	~ 10 cm ~ 5 ns	real time	four times daily	15 min
Ultra Rapid (observed half)	orbits sat. clocks	< 5 cm ~ 0.2 ns	3 hours	four times daily	15 min
Rapid	orbits sat. clocks	< 5 cm 0.1 ns	17 hours	daily	15 min 5 min *
Final	orbits sat. clocks	< 5 cm < 0.1 ns	~ 13 days	weekly	15 min 5 min **

* CODE 30 seconds

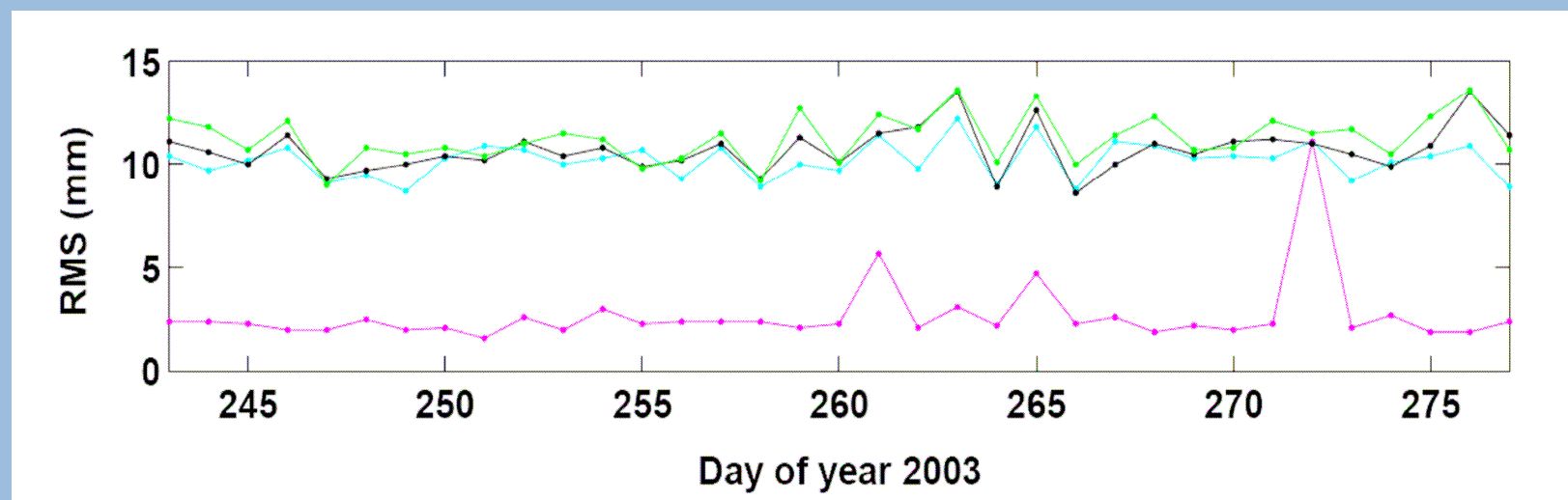
** CODE, JPL and EMR 30 seconds

The CODE Analysis Center contributes to all of these IGS products.

IGS / CODE / AIUB

- > The BSW is capable to do precise orbit determination for Low Earth Orbiters (LEOs):
 - Longer POD time series for CHAMP and GRACE satellites exist
 - Tests with other LEOs, e.g. COSMIC, SAC-C, MetOp
 - AIUB is responsible for the Precise Science Orbit of the GOCE satellite (member of the GOCE High-level Processing Facility)

GRACE K-band range RMS errors (**ZD**, **DD**, **DD comb**, **DD amb. fixed**)



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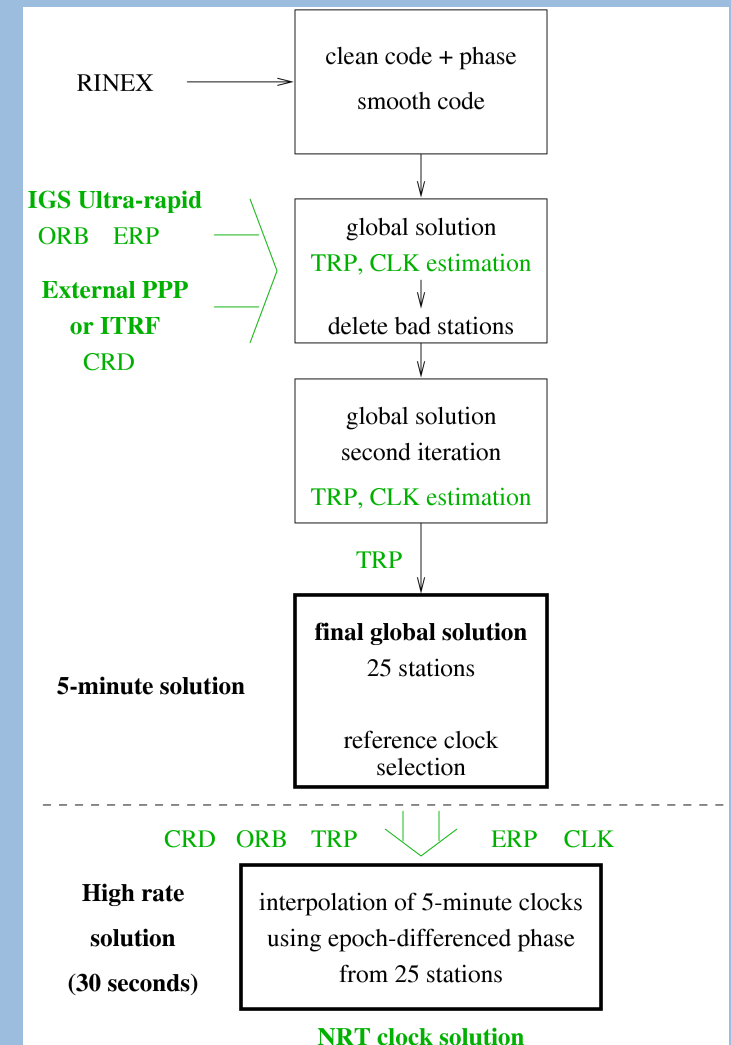
NRT GPS clock generation

Available NRT GPS products:

- > IGS Ultra-rapid (predicted part) **IGUp**
 - ✓ free of charge
 - ✗ quality of clock corrections
- > JPL Real-Time Generated **RT**
 - ✗ commercial
 - ✓ available within 1-2 minutes after observation
- > Self generated NRT product **IGUp+c**
 - IGS Ultra-rapid orbits (predicted part) + generation of NRT GPS clock corrections based on a NRT station network
 - ✓ Consistency of orbits and clocks within the processing software which is also a big advantage for LEO POD

NRT GPS clock generation

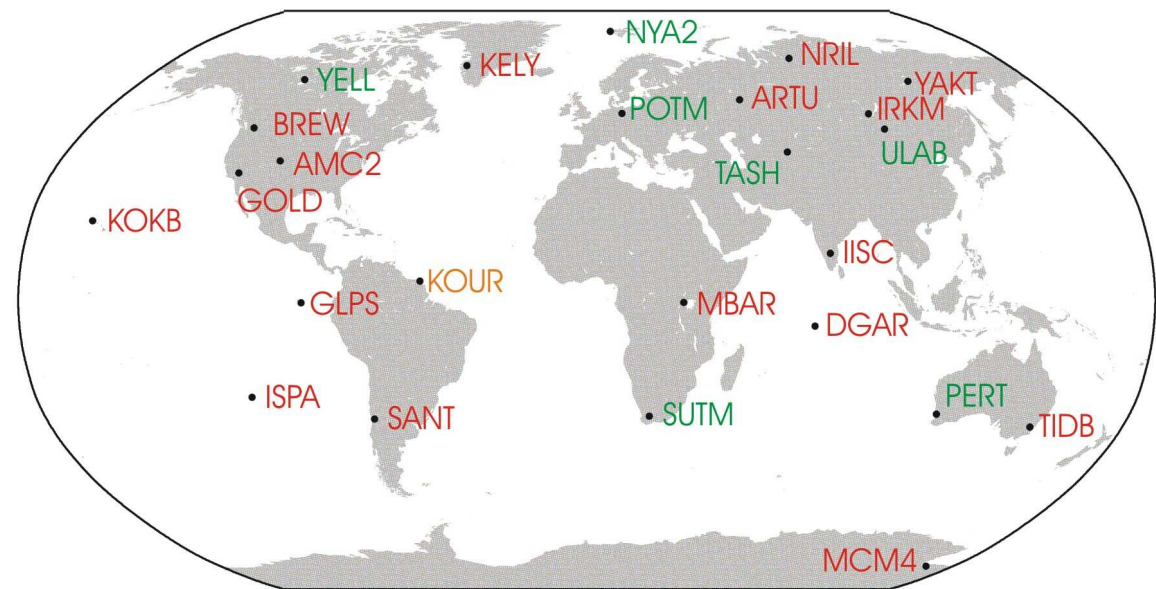
- > Zero-difference procedure is derived from the CODE rapid and final clock processing schemes
- > 25 globally distributed stations
- > Data cleaning and code smoothing
- > IGS Ultra-rapid orbits and pole information introduced
- > Two iterations for post-fit residual screening (troposphere delay estimation)
- > Final global solution for clock estimation (5 minutes sampling, smoothed code, carrier phase)
- > Interpolation to 30 seconds (epoch-differenced carrier phase)



Example (7-9 October, 2006): Subnet of IGS 1Hz network

IGS 1 Hz network:

- 15 min data batches
- nominal latency < 5 min
- 25 stations (globally distributed)
- Latency of station data:
~ 70% > 60 min
=> Future alternative:
real-time data stream



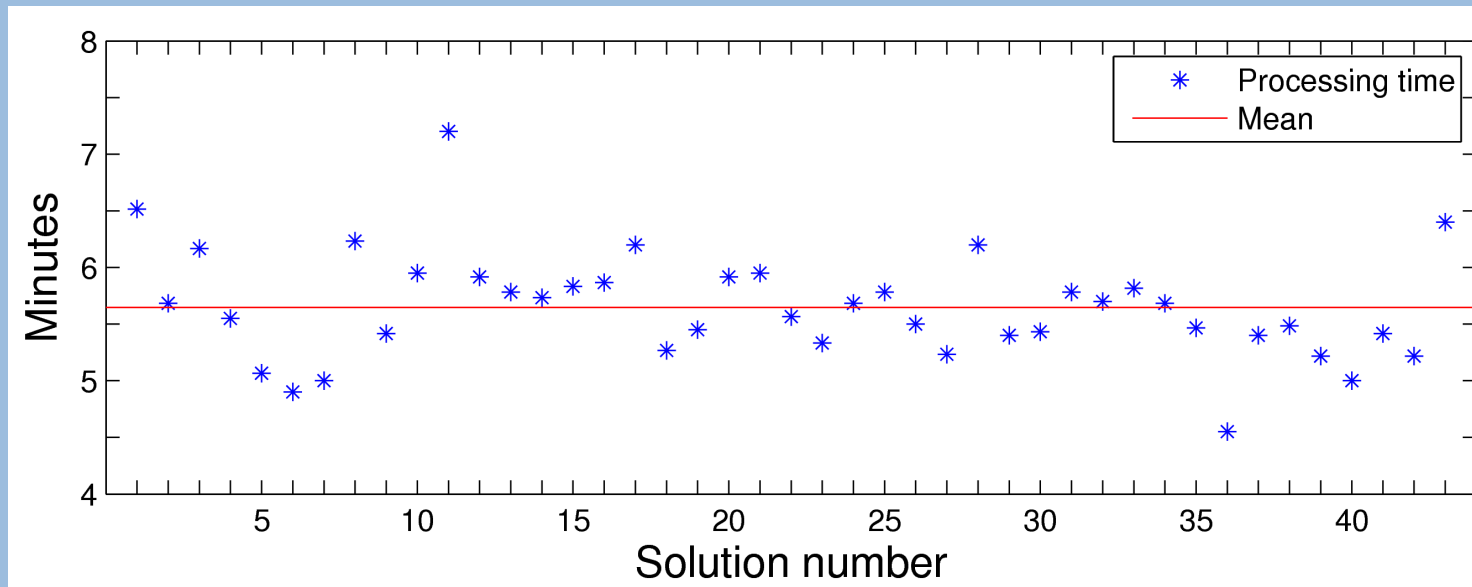
GM 2006 Dec 5 16:45:15

Example: NRT processing scheme

Solution	Date	start time	end time	IGS Ultra Orbits
01	7 Oct. 2006	00:20:00	03:20:00	igu13956_00.sp3
02		02:00:00	05:00:00	igu13956_00.sp3
03		03:40:00	06:40:00	igu13956_00.sp3
04		05:20:00	08:20:00	igu13956_00.sp3
05		07:00:00	10:00:00	igu13956_06.sp3
06		08:40:00	11:40:00	igu13956_06.sp3
07		10:20:00	13:20:00	igu13956_06.sp3
08		12:00:00	15:00:00	igu13956_12.sp3
09		13:40:00	16:40:00	igu13956_12.sp3
...	

- 43 solutions à 3 hours, updates every 100 minutes
- Most recent IGS Ultra-rapid orbit is used

Example: NRT clock generation, processing time

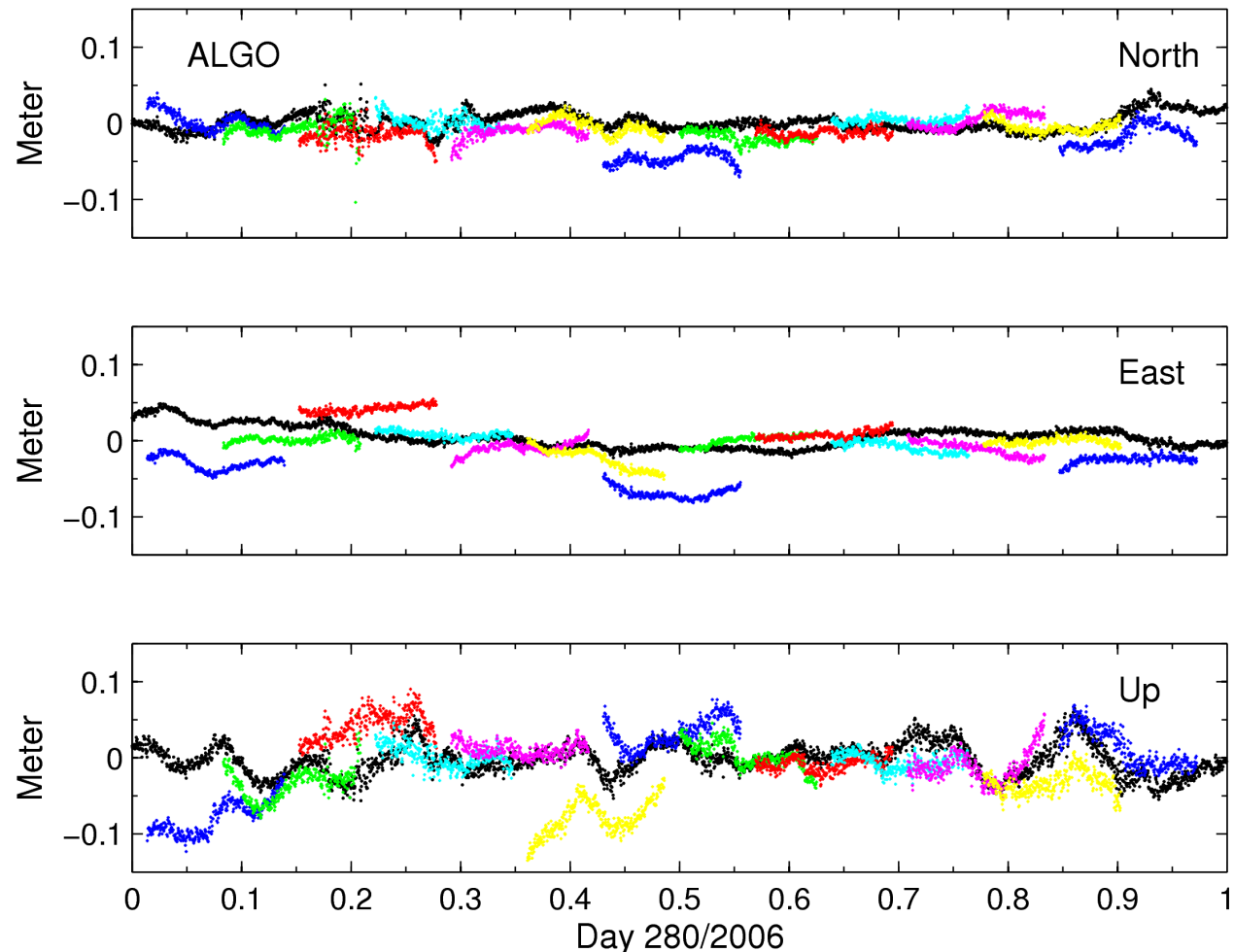


- Linux Cluster of the University (about 500 nodes)
 - Parallel jobs if possible
- => Processing time is non-critical for NRT applications

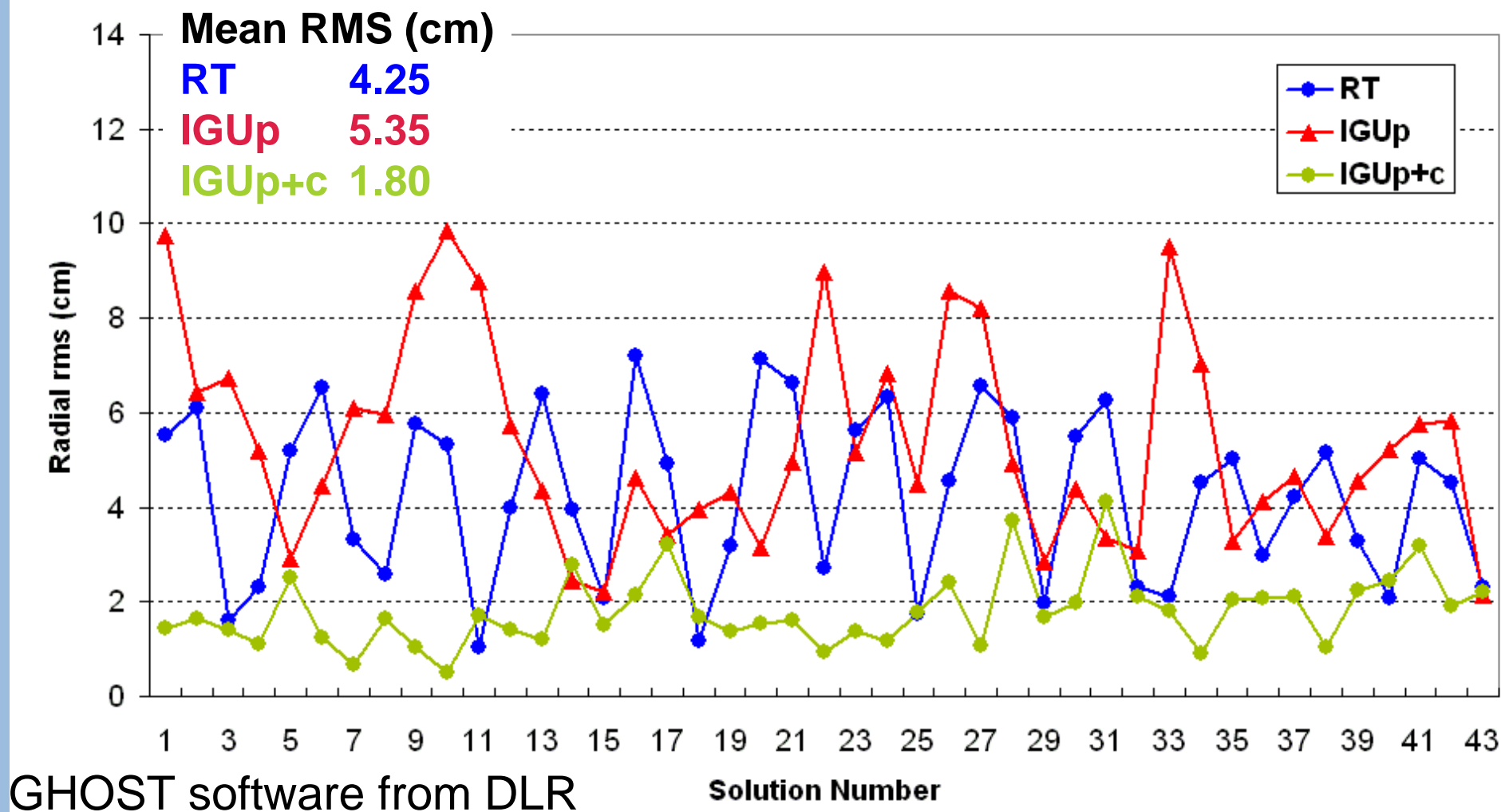
Validation of the NRT clocks

Kinematic precise point positioning of ground station:

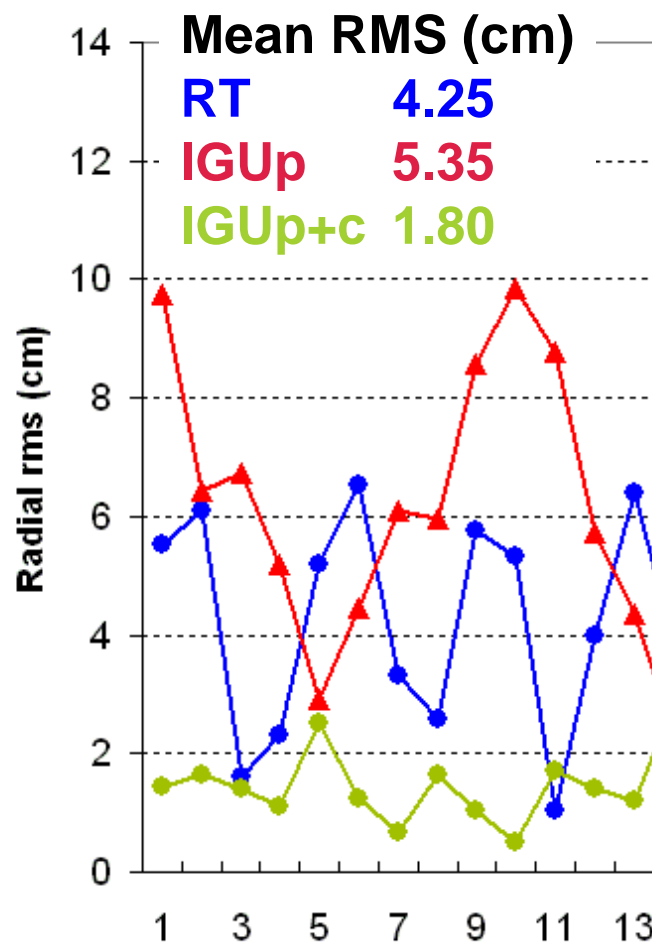
- Black: reference solution, CODE final products used
 - Other colors: IGS Ultra-rapid orbits and newly generated NRT clocks used
- agreement < 10 cm, even for the Up component \Leftrightarrow radial component of LEO



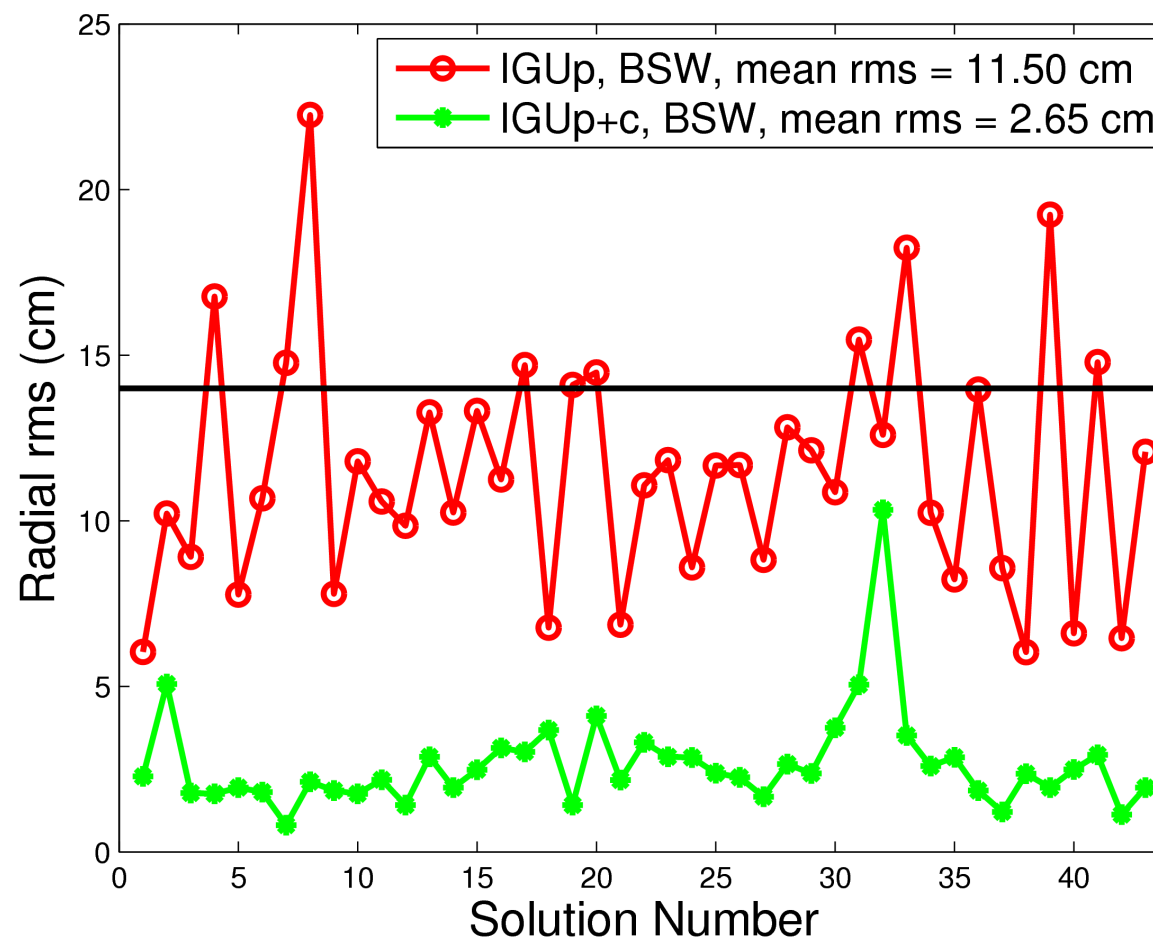
GRACE NRT POD (1)



GRACE NRT POD (1)



GHOST software from DLK



GRACE NRT POD (2)

- > Different NRT GPS products are used for NRT POD of one GRACE satellite (GHOST software)
- > The POD solutions using the new **IGUp+c** product show the best performance compared with the JPL Level 1 B orbit solution (mean radial rms: 1.8 cm)
- > NRT POD solutions with the BSW (full consistency) show the same relative improvement when using **IGUp+c** instead of **IGUp**.
- > Reduced-dynamic orbit solutions in BSW are less dynamic than in GHOST, i.e. they are closer to a kinematic solution.

Summary

- > The AIUB is host of CODE, one of the IGS analysis centers.
- > From the processing scheme in the framework of IGS a NRT GPS clock generation procedure has been developed.
- > This procedure could be set up to support NRT POD for LEO missions.
- > Tests with GRACE data (using the in-house and an independent GPS processing software) have shown an enormous improvement of the NRT POD results compared to currently available NRT GPS products.
- > Based on the experience in the field of GNSS POD the AIUB is capable to perform LEO POD in a reduced-dynamic and fully kinematic mode using the Bernese GPS Software.