

On the combination of gravity field time series derived from kinematic positions of Low Earth Orbiting satellites

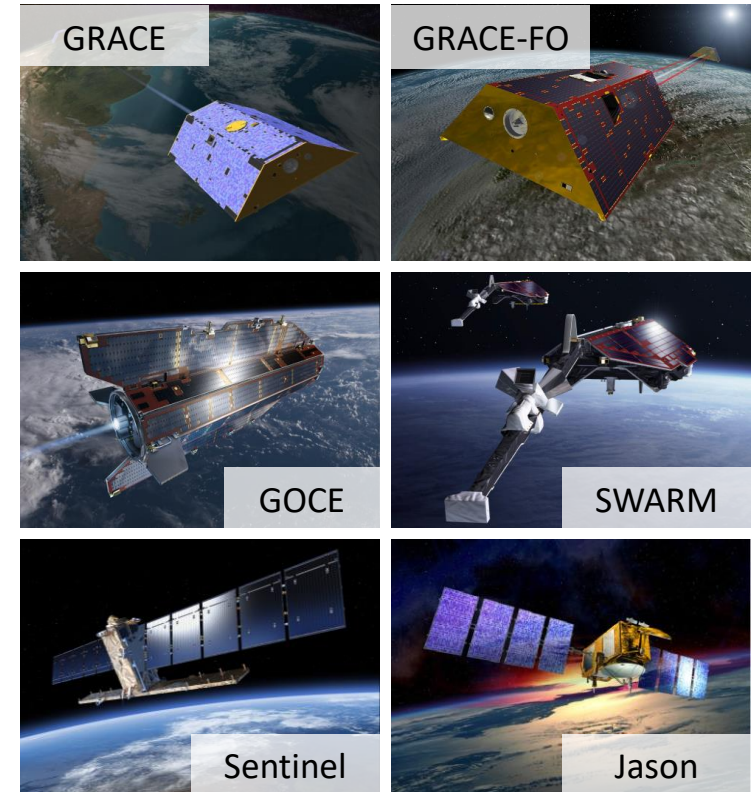
Thomas Grombein, Martin Lasser,
Daniel Arnold, Ulrich Meyer, Adrian Jäggi

Astronomical Institute
University of Bern, Switzerland

Contact: thomas.grombein@aiub.unibe.ch

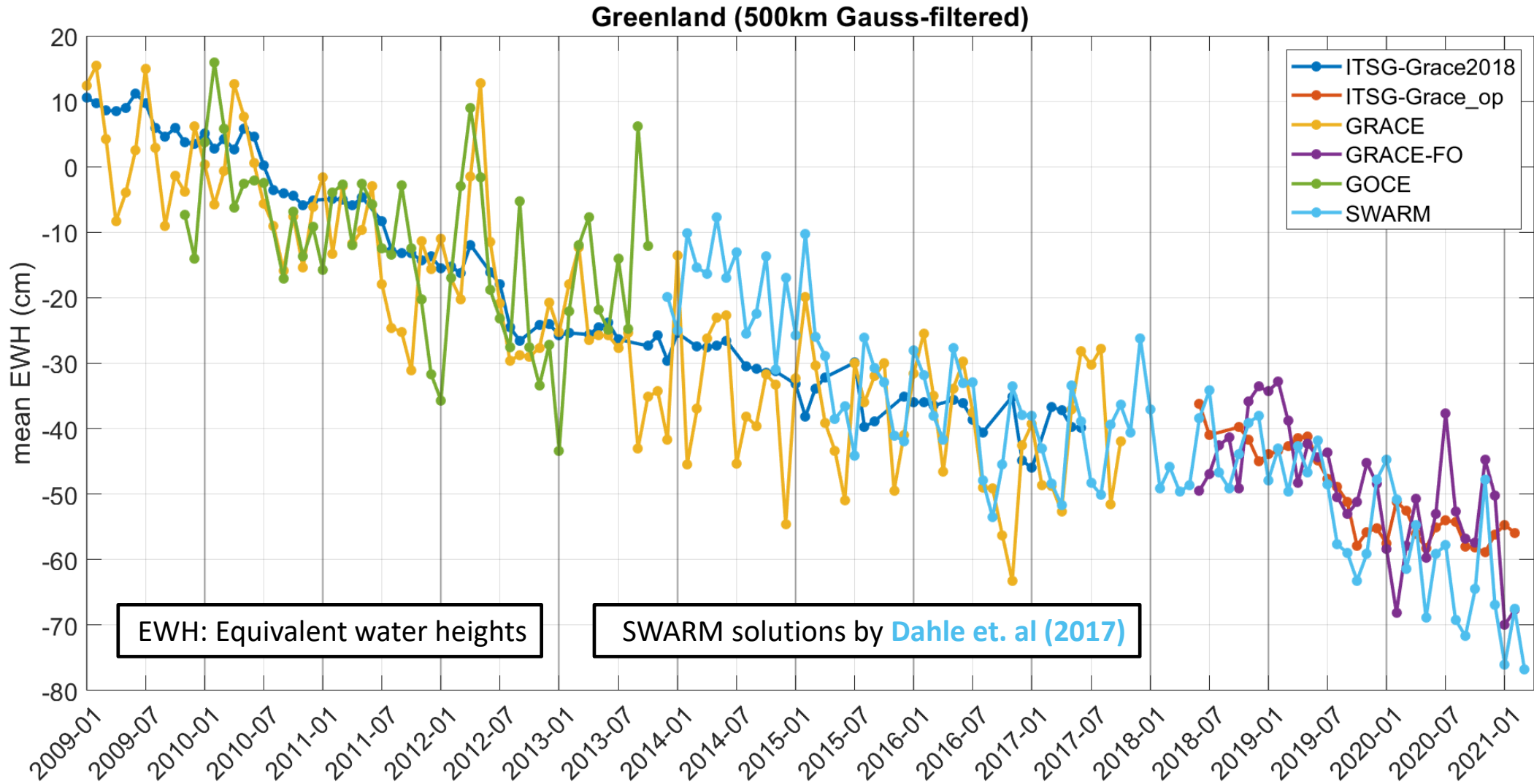
Introduction

- **Motivation**
 - Any Low Earth Orbiting (LEO) satellite with a GPS receiver may serve as a gravity field sensor (in addition to dedicated missions)
 - Kinematic LEO positions are used for gravity field recovery in a generalized orbit determination problem
- **Our goal:** Multi-LEO gravity field time series taking advantage of
 - Large number of observations
 - Complementary orbital configurations
- **Focus here:** Combination of monthly LEO gravity field time series



Source: ESA, NASA

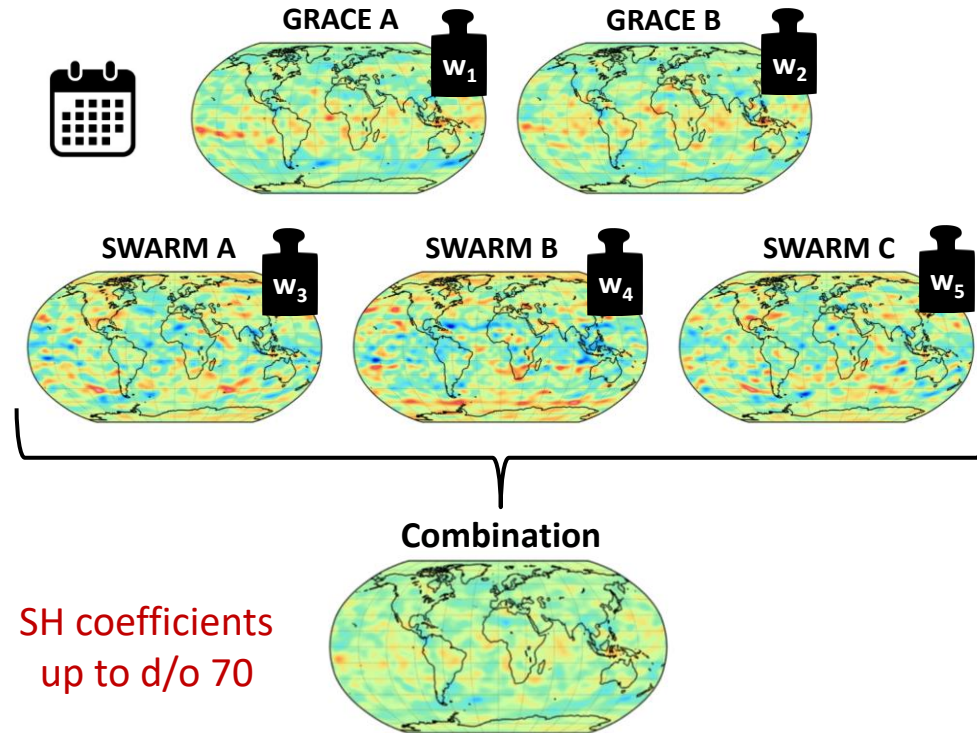
Overview of LEO gravity field time series



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Combination of monthly gravity field time series

- Combination strategy on solution level
 - Combination of individual satellite solutions
 - Monthly field-wise weights



- Variance component estimation (VCE)
 - SH coefficients are used as pseudo-observations
 - Field-wise weights (Jean et. al, 2018):

$$w_{i,k} = \left(1 - \frac{w_{i,k-1}}{\sum_i w_{i,k-1}} \right) \frac{1}{\text{RMS}(\mathbf{x}_i - \hat{\mathbf{x}}_{k-1})^2}$$

$$w_{i,0} = 1/n_{\text{sol}}$$

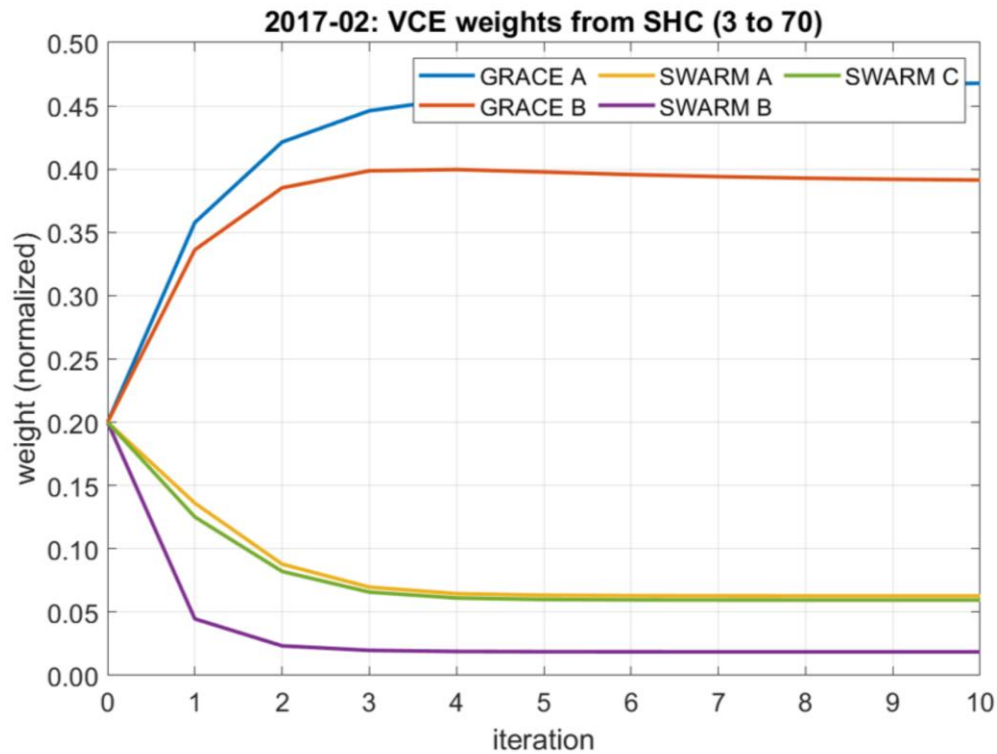
- Combination in iteration step k:

$$\hat{\mathbf{x}}_k = \frac{1}{\sum_i w_{i,k}} \sum_i w_{i,k} \mathbf{x}_i$$

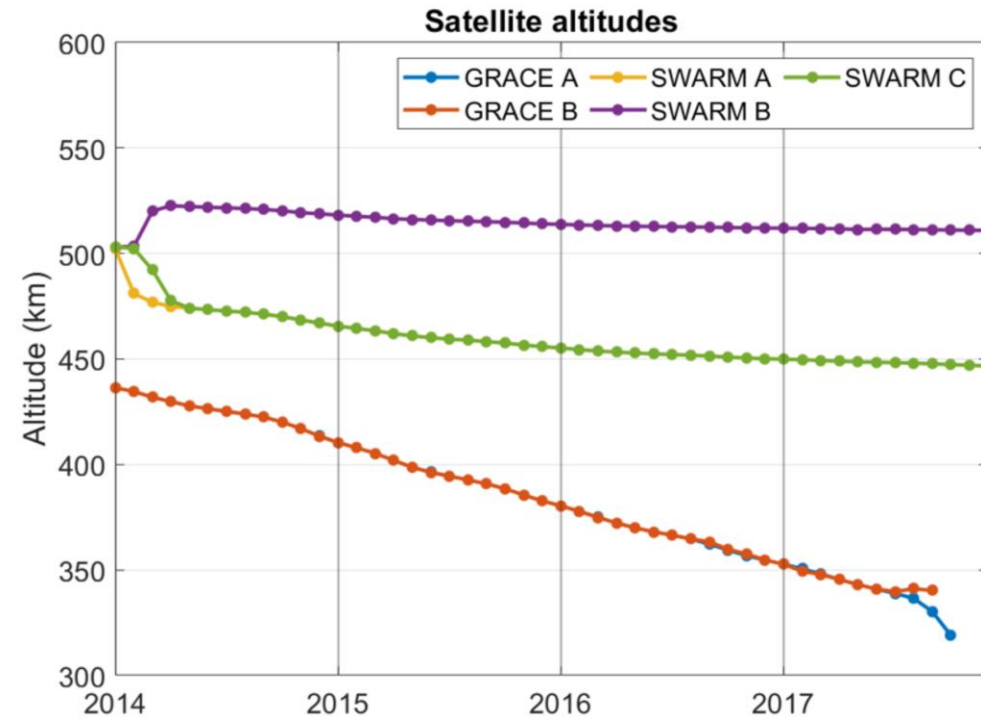
SH coefficients of solution i

Variance component estimation: GRACE/SWARM

- Weights based on unfiltered SHC



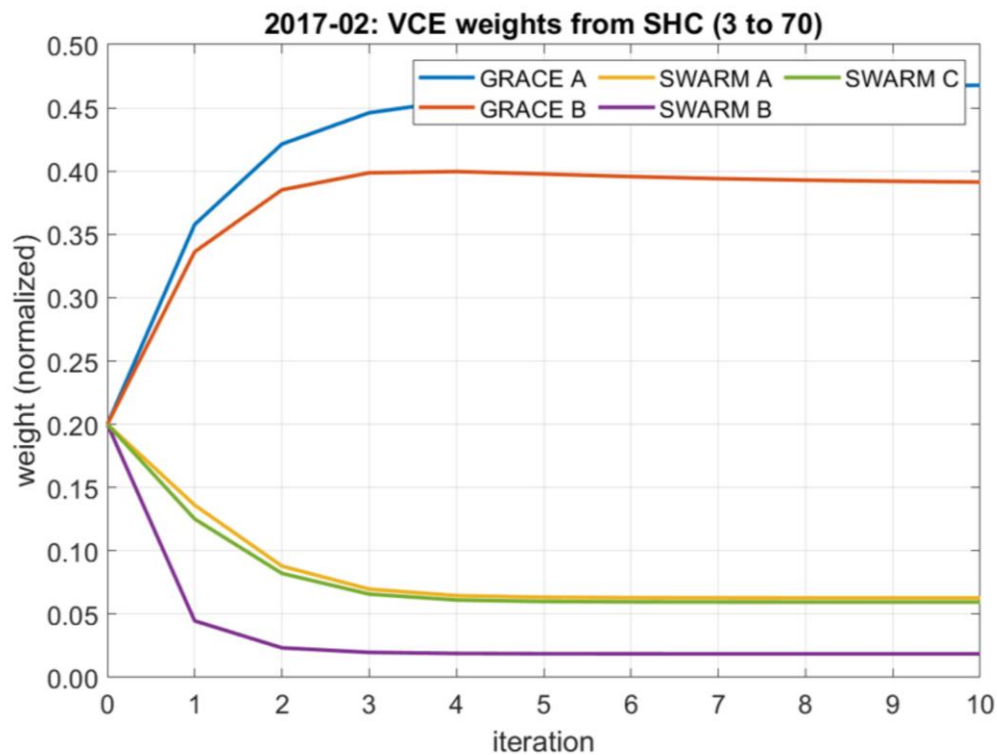
- Satellite altitudes



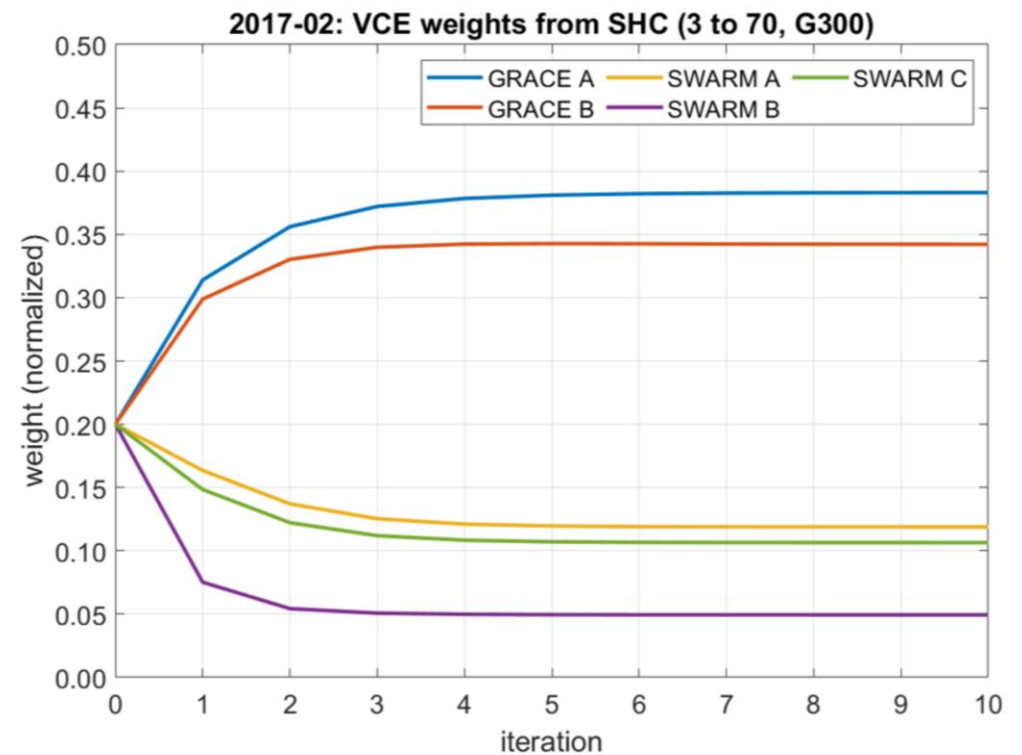
- Weights are dominated by the noise of the high-degree coefficients

Variance component estimation: GRACE/SWARM

- Weights based on unfiltered SHC

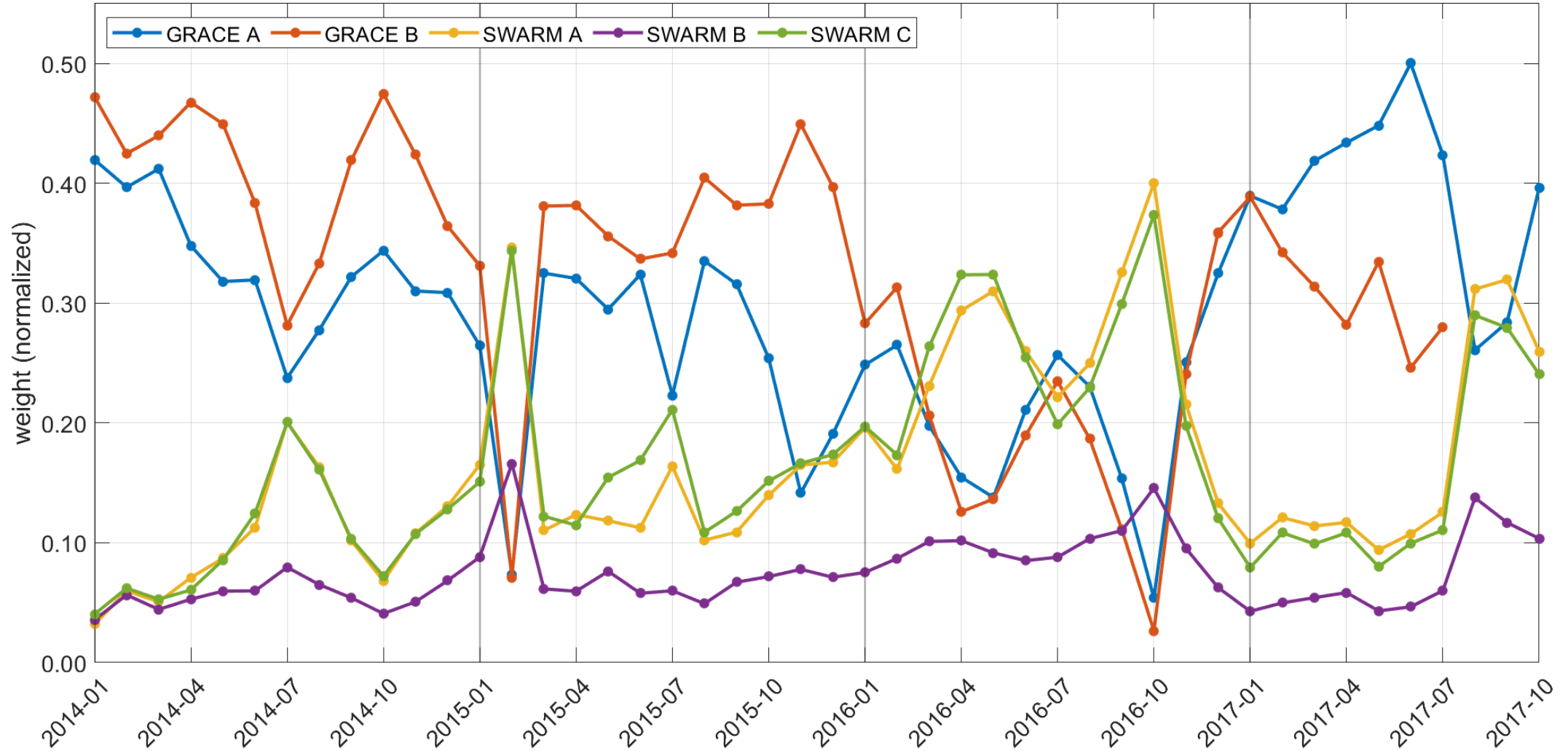


- Weights based on filtered SHC ([here](#): 300km Gauss)



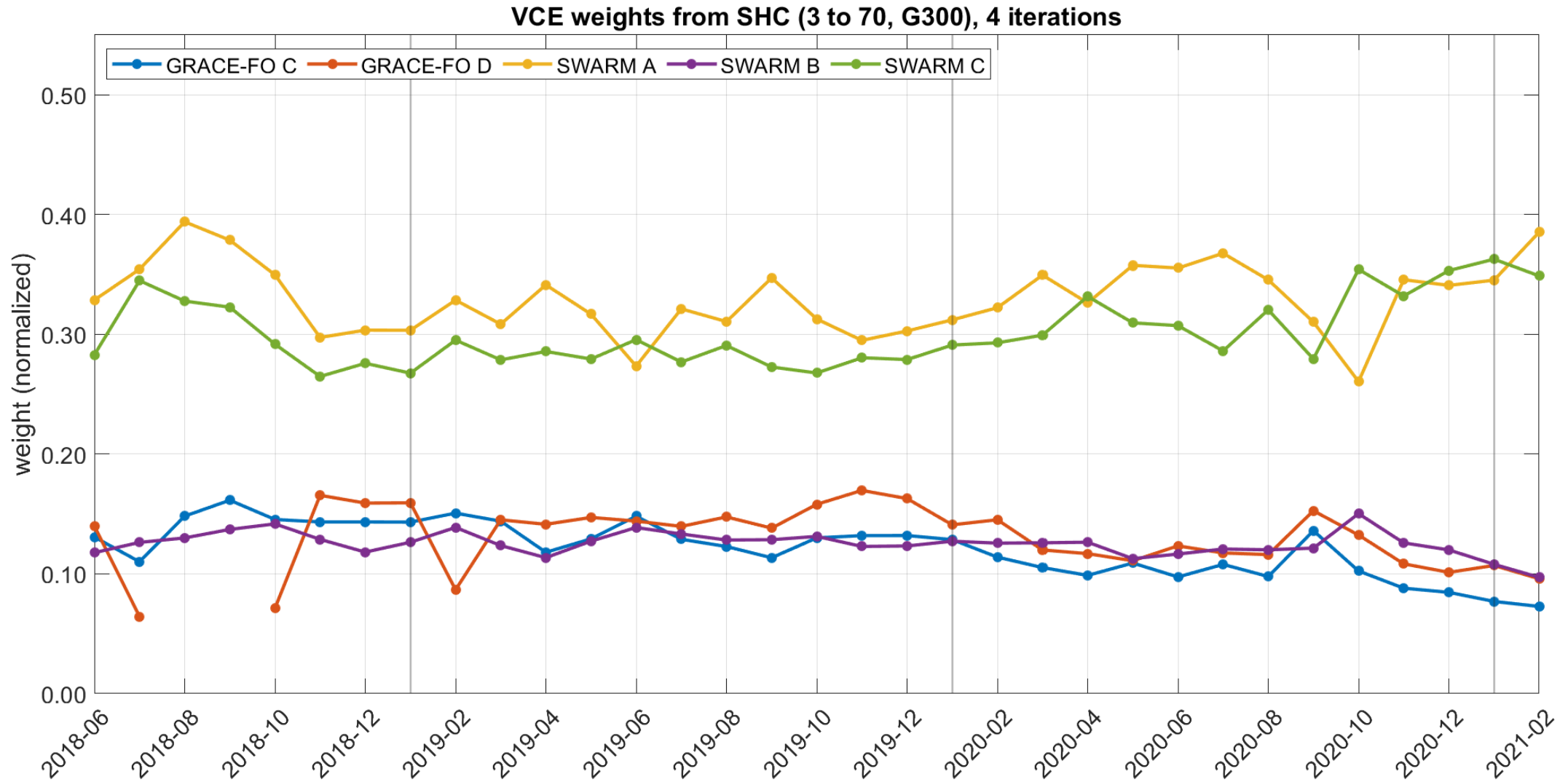
Variance component estimation: GRACE/SWARM

VCE weights from SHC (3 to 70, G300), 4 iterations



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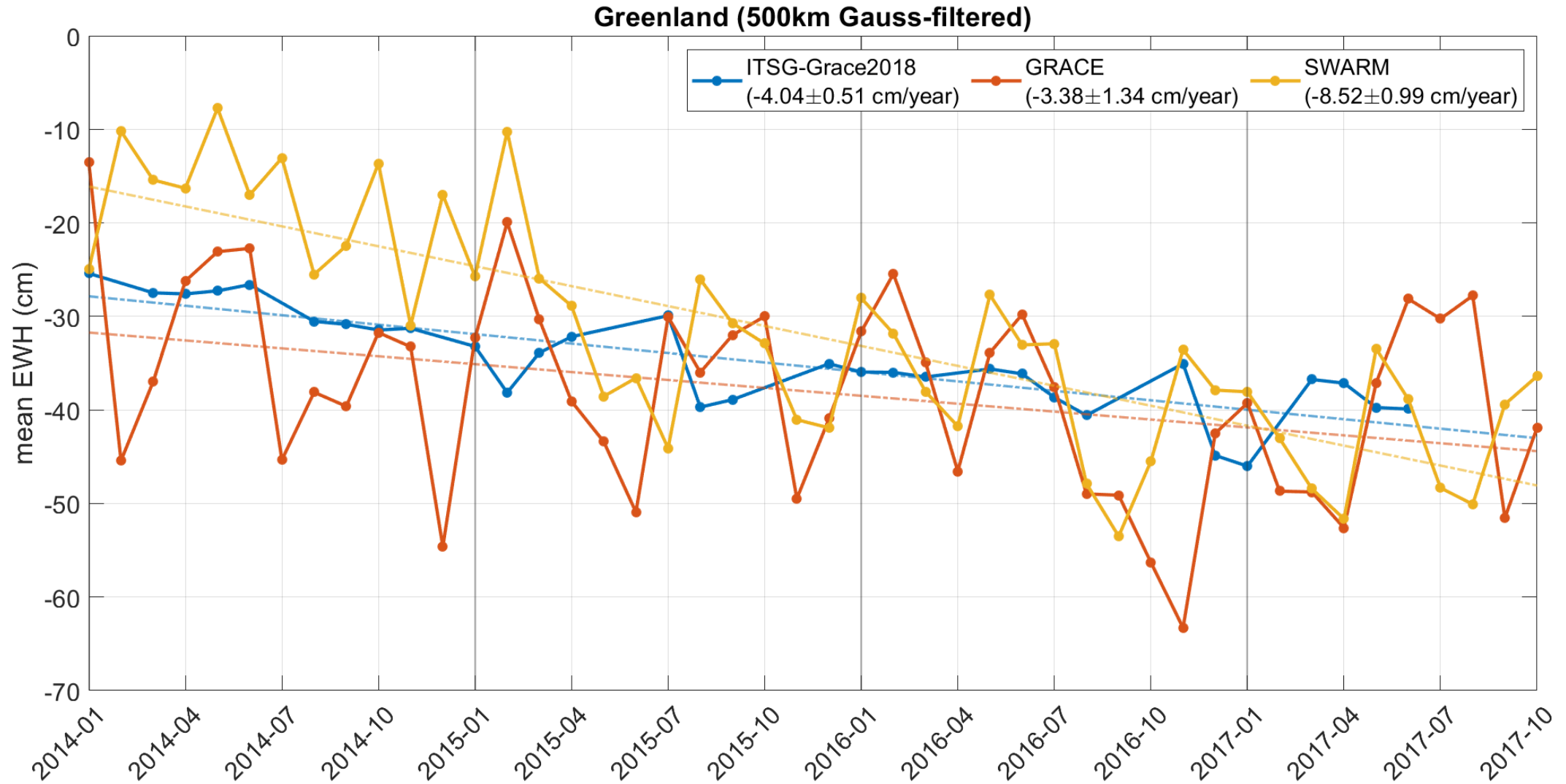
Variance component estimation: GRACE-FO/SWARM



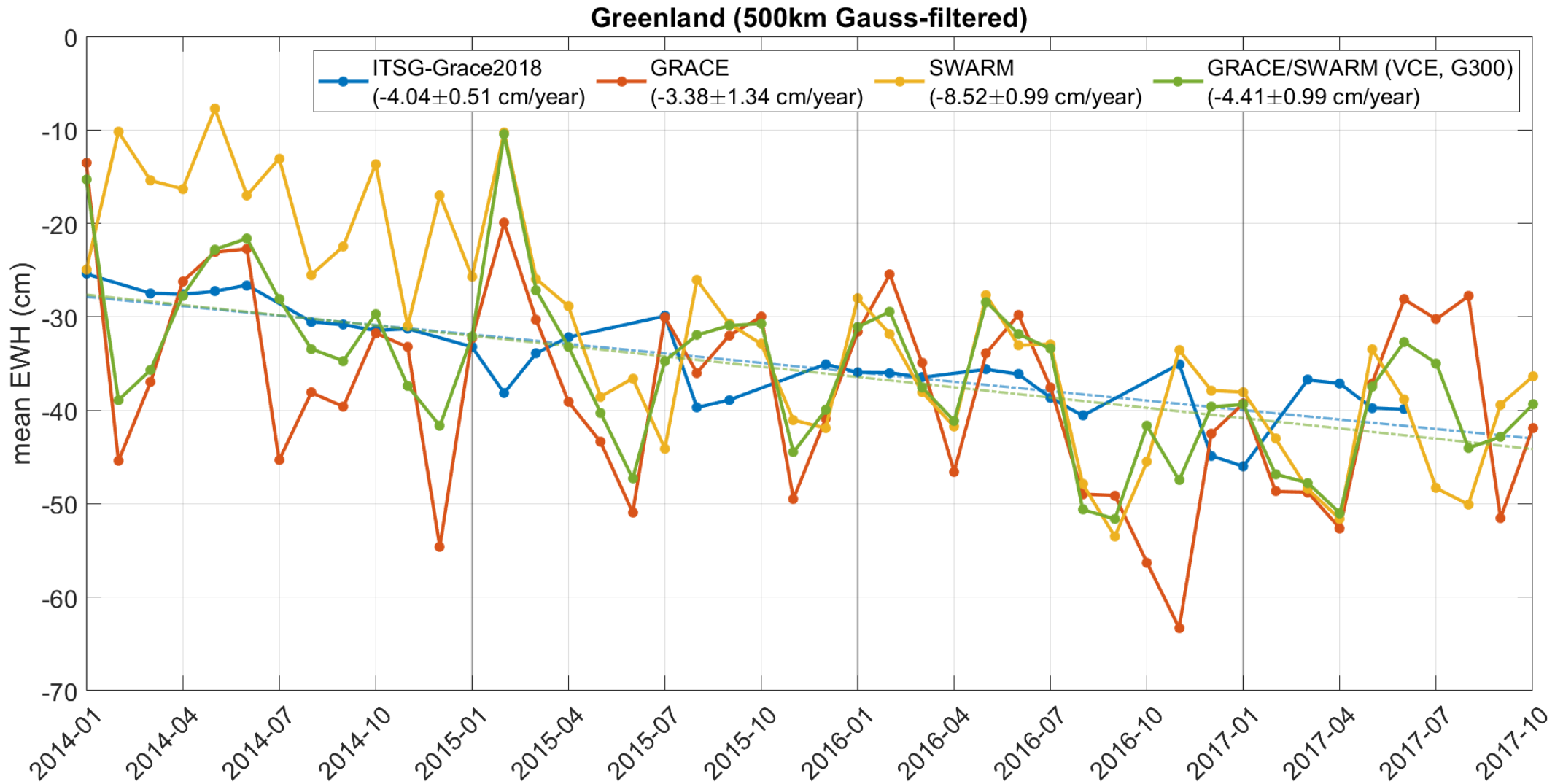
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Evaluation of mass trends and changes

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Evaluation of mass trends and changes

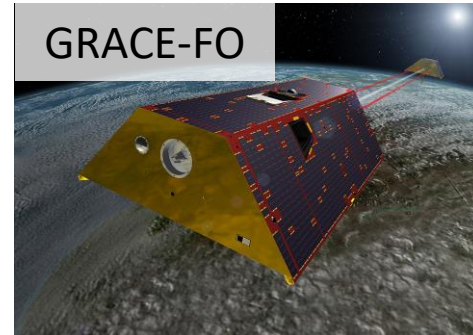
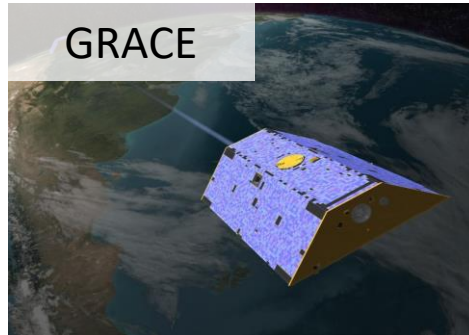


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Summary and Outlook

- Time-variable gravity field recovery from kinematic LEO positions
- Combination of monthly LEO gravity field time series on solution level
- Combination of GRACE/-FO and SWARM time series
 - Field-wise weights derived from variance component estimation
 - Filtering helps to reduce the impact of high-degree coefficients on the VCE weights
 - Combined time series provide an improved estimation of mass trends and changes
- Next steps
 - VCE settings still need to be optimized → choice of applied filter, iteration
 - Combination of LEO gravity field time series on normal equation level
 - Extension of GRACE/-FO time series + inclusion of new LEO satellites

Thank you for your attention



Source: ESA, NASA

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References

[Dahle C, Arnold D, Jäggi A \(2017\)](#): Impact of tracking loop settings of the Swarm GPS receiver on gravity field recovery. *Advances in Space Research* 59(12):2843–2854, DOI:10.1016/j.asr.2017.03.003

[Jean Y, Meyer U, Jäggi A \(2018\)](#): Combination of GRACE monthly gravity field solutions from different processing strategies. *Journal of Geodesy* 92:1313–1328, DOI: 10.1007/s00190-018-1123-5