Comparison of GOCE-GPS gravity fields derived by different approaches

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Summarv

AAA

Several approaches have been proposed to extract gravity field information from the GPS-derived kinematic GOCE (Gravity field and steady-state Ocean Circulation Explorer) orbits. Although there is a general consensus that, except for energy balance, these methods theoretically provide equivalent results, GOCE-GPS solutions based on real data have never been compared with each other within a consistent data processing environment so far. This contribution strives to close this gap. The gravity field solutions considered here make use of the

- CMA Celestial Mechanics Approach [1] computed at AIUB (U Bern)
- SAA Short-Arc Approach [2]
- computed at ITSG (TU Graz) Averaged Acceleration Approach [3] computed at DEOS (TU Delft)
- PAA Point-wise Acceleration Approach [4] computed at GIS/IWF (U Stuttgart/Austrian Acad. of Sciences)
- EBA Energy Balance Approach [5]
- computed at INAS (TU Graz)

Formal errors: empirical errors & geoid height differences (w.r.t. ITG-Grace2010s)

40 CMA 60 100 50 100 -50 20 40 SAA 100 50 -100 -50 50 100 -50 0 40 AAA 60 100 -50 50 PAA 60 100 -50 50 100 -50 0 50 EBA ň $s_{in} \leftarrow Order \rightarrow c_{in}$ $s_{in} \leftarrow Order \rightarrow c_{in}$ 50 50 -11 -10.5 -10 -9.5 -9 -8.5 -2.5 -2 -1.5 -1 -0.5 formal errors (log10) empirical relative errors (log10)

aeoid height differences (cm), smoothing 500km

Processing details

	СМА	SAA	AAA	PAA	EBA
Orbit data	ESA SST_PKI product (reprocessed kinematic GOCE orbit)				
Variance-covariance data	ESA SST_PCV product		no	ESA SST_PCV product	
Period	1.11.2009-11.1.2010 (R1)				
Spectral resolution		130		120	100
Regularization	no				
A priori information	EGM96			no	
Background models	according to IERS Conventions 2003/2010				
Non-gravitational accel.	ye	S		no	yes
Empirical accelerations	ye	S		no	

Degree-error RMS: geoid error

Orders $\leq |0.5\pi - I|l$ (inclination I in rad) omitted [6]



All orders considered



Accumulated geoid height errors



SLR tracking residuals (obs.-comp.)

Parameterization: monthly arcs Estimated parameters: state vectors (1/arc), station coordinates (1/arc), drag coefficients (1/day), constant empirical accelerations (1/day), measurement biases (1/station and arc)

Lageos1 (up to degree and order 20)



c20 coefficient replaced by SLR-derived value



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