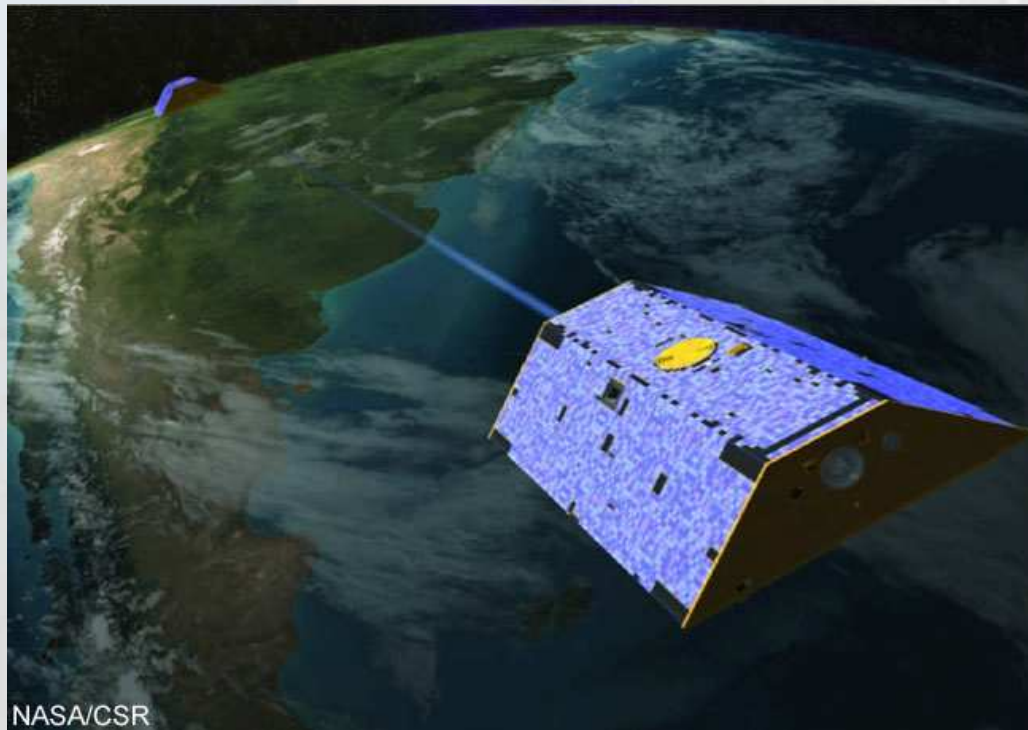


# GPS Single-frequency Orbit Determination for Low Earth Orbiting Satellites

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# Motivation

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*Nowadays, orbit accuracies of a few cm's are reached for low Earth orbiting satellites (LEOs) using GPS **dual**-frequency (DF) observations.*

# Motivation

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=> *Which orbit accuracies are possible with GPS **single**-frequency (SF) OD?*

1. Which is the best solution/possibility to handle the ionospheric effect in the observations?
2. How good does the pre-processing work?
3. Is the orbital height and/or the data sampling rate an important quality factor?

# Data description

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- Days 273-279 (Sep 30 – Oct 06), 2007
- GPS: CODE final orbits and clocks
- GRACE A and B, 10 sec
  - ~ 470 km altitude
- MetOp, 1 sec (from ESA/EUMETSAT)
  - ~ 820 km altitude
- Reduced-dynamic orbit solutions with 6 min  
piecewise constant accelerations in RSW-system
- Reference solutions: dual-frequency reduced-dynamic orbits

# 1. Handling of the ionospheric effect

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Ionospheric effect in the SF observations can be reduced

**A:** by modelling the effect using Global Ionosphere Maps (GIMs)

only L1 (carrier-phase) observations

**B:** by forming ionosphere-free linear combination between the code and the phase observation of the available frequency  $(L1 + C1)/2$  (GRAPHIC combination)

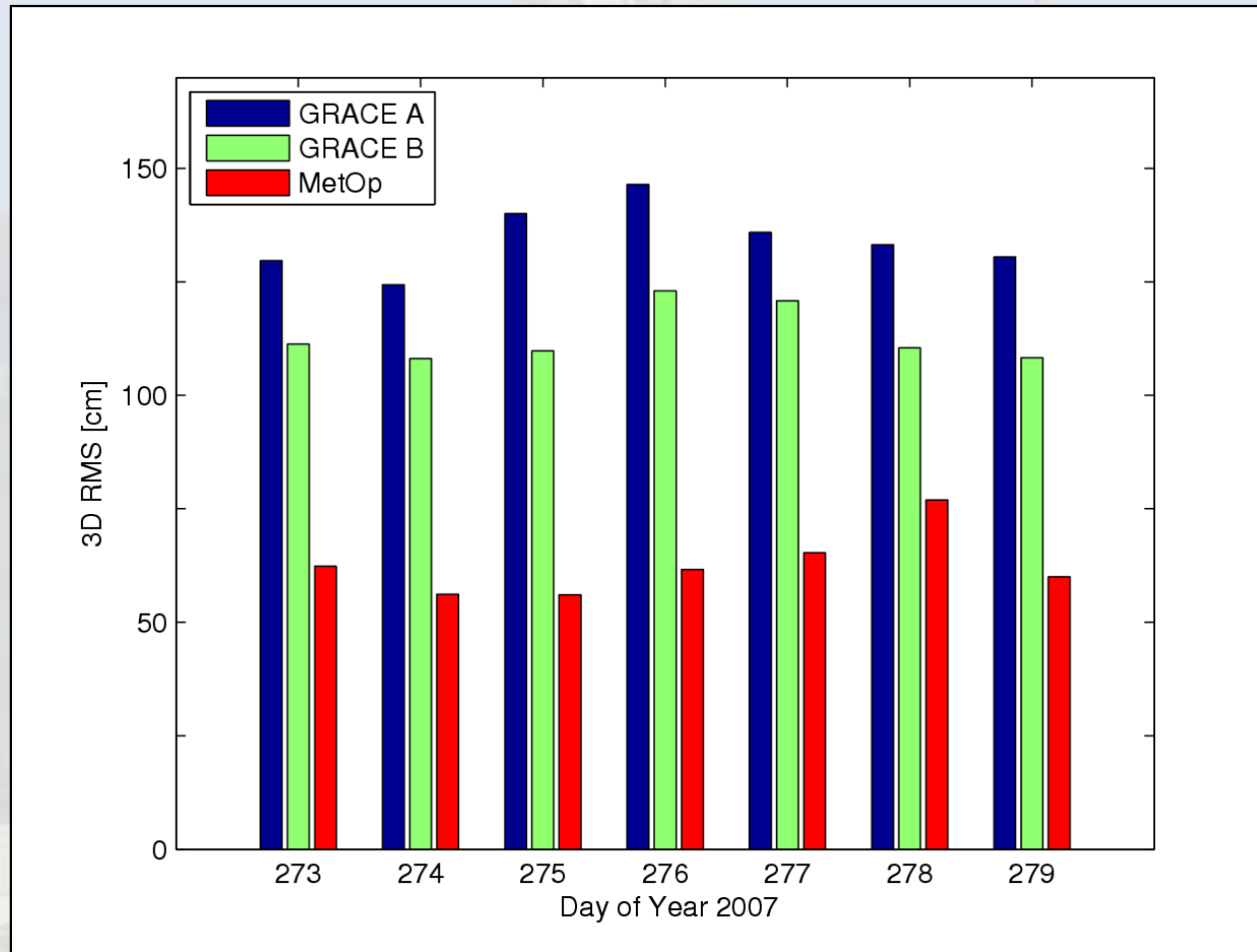
L1 and C1 (code) observations

**C:** by estimating Stochastic Ionosphere Parameters (SIPs), one per epoch and satellite link, e.g., 10 satellites are tracked at one epoch => 10 SIPs for this epoch

L1 and C1 observations



# 1. Handling ionosphere effect: no

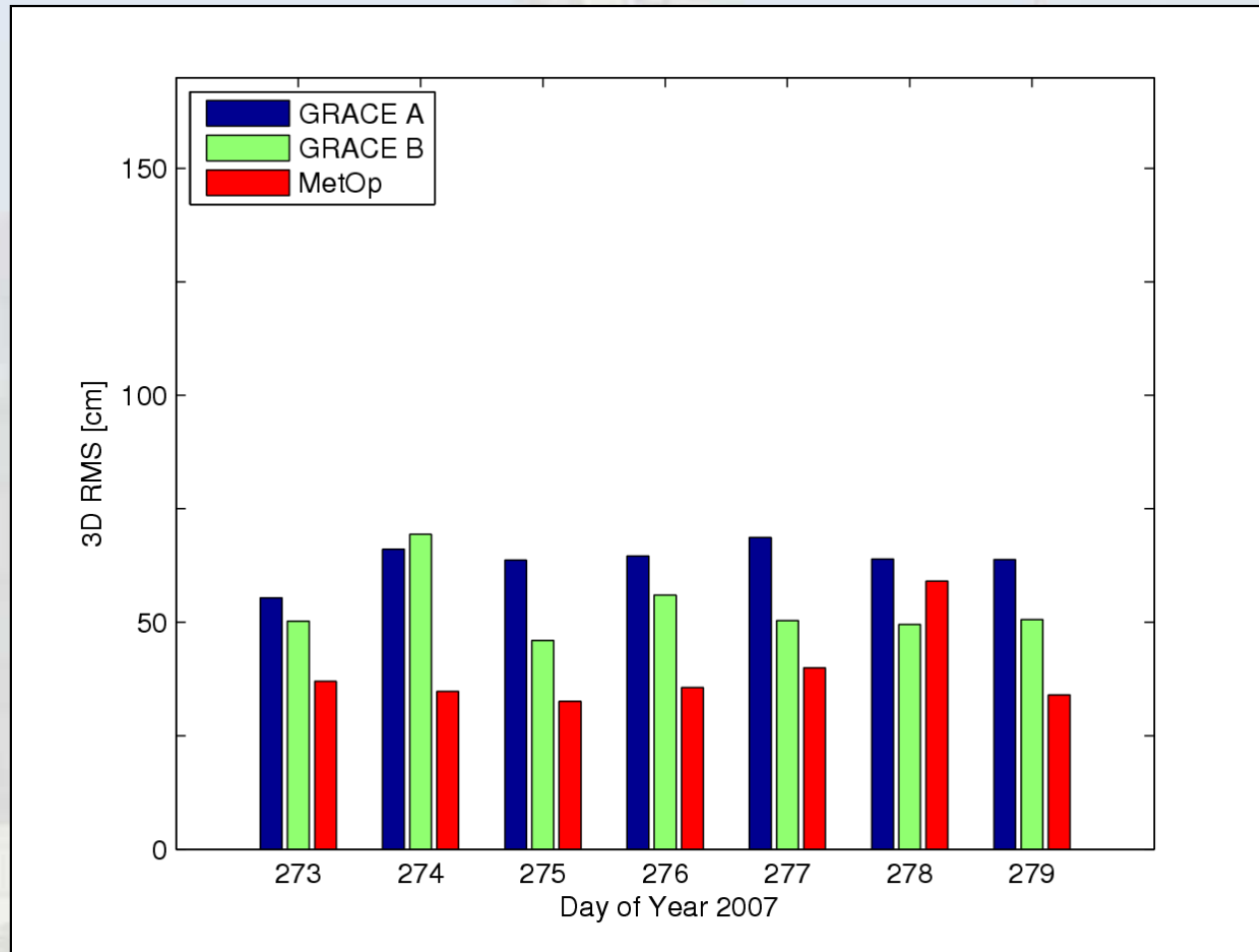


Mean 3D RMS:  
134.3 cm  
113.1 cm  
62.6 cm

- Phase (L1) solution
- **MetOp** is at higher altitude
- **GRACE A** phase data quality is worse than for **GRACE B**

Pre-processing based on DF data (L1/L2), 10 sec

# 1. Handling ionosphere: Solution A - GIMs



Mean 3D RMS:

63.7 cm

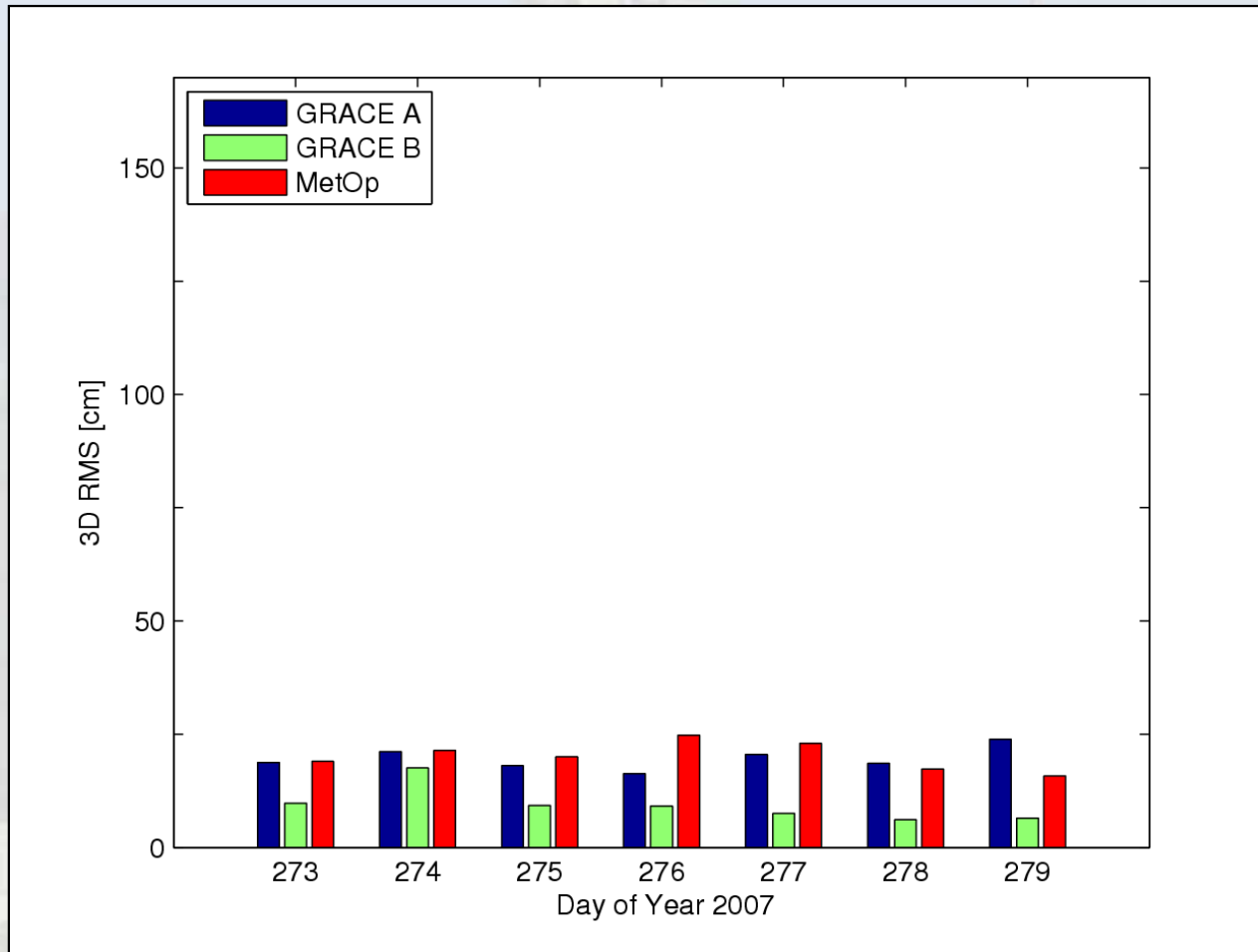
53.2 cm

39.0 cm

50-60% improvement  
(mainly in radial  
direction) by modelling  
ionosphere

Pre-processing based on DF data (L1/L2), 10 sec

# 1. Handling ionosphere: Sol B - GRAPHIC

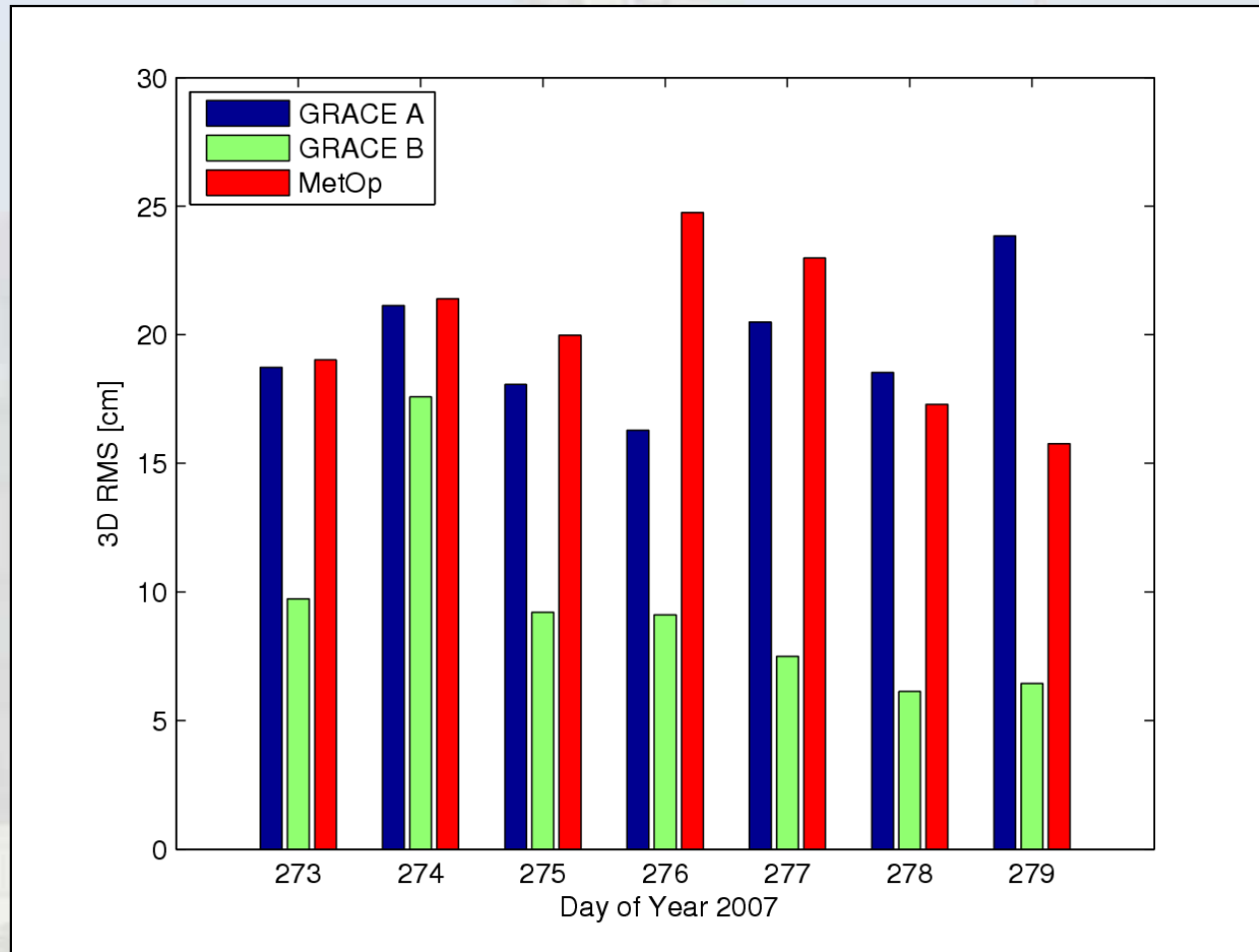


Mean 3D RMS:  
19.6 cm  
9.4 cm  
20.2 cm

Pre-processing based on DF data (L1/L2 and C1/P2), 10 sec



# 1. Handling ionosphere: Sol B - GRAPHIC



Mean 3D RMS:

19.6 cm

9.4 cm

20.2 cm

**GRACE A:**

Data quality worse (occultation antenna)

**GRACE B:**

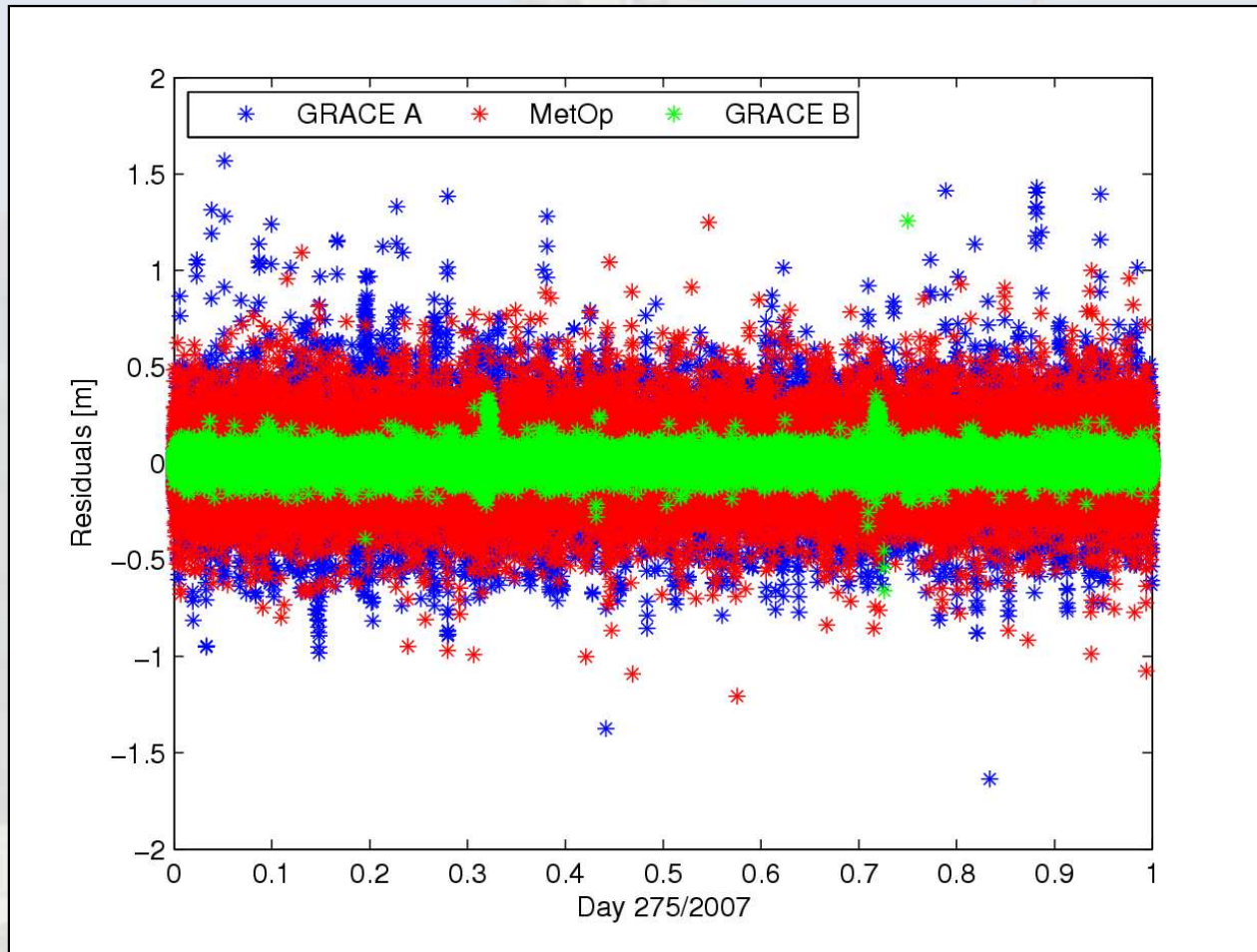
C/A-code noise is very low (~10 cm)

**MetOp:**

Observation noise is ~3 times larger than for GRACE B

Pre-processing based on DF data (L1/L2 and C1/P2), 10 sec

# 1. Handling ionosphere: Sol B - GRAPHIC



Mean 3D RMS:

19.6 cm

9.4 cm

20.2 cm

**GRACE A:**

Data quality worse  
(occultation antenna)

**GRACE B:**

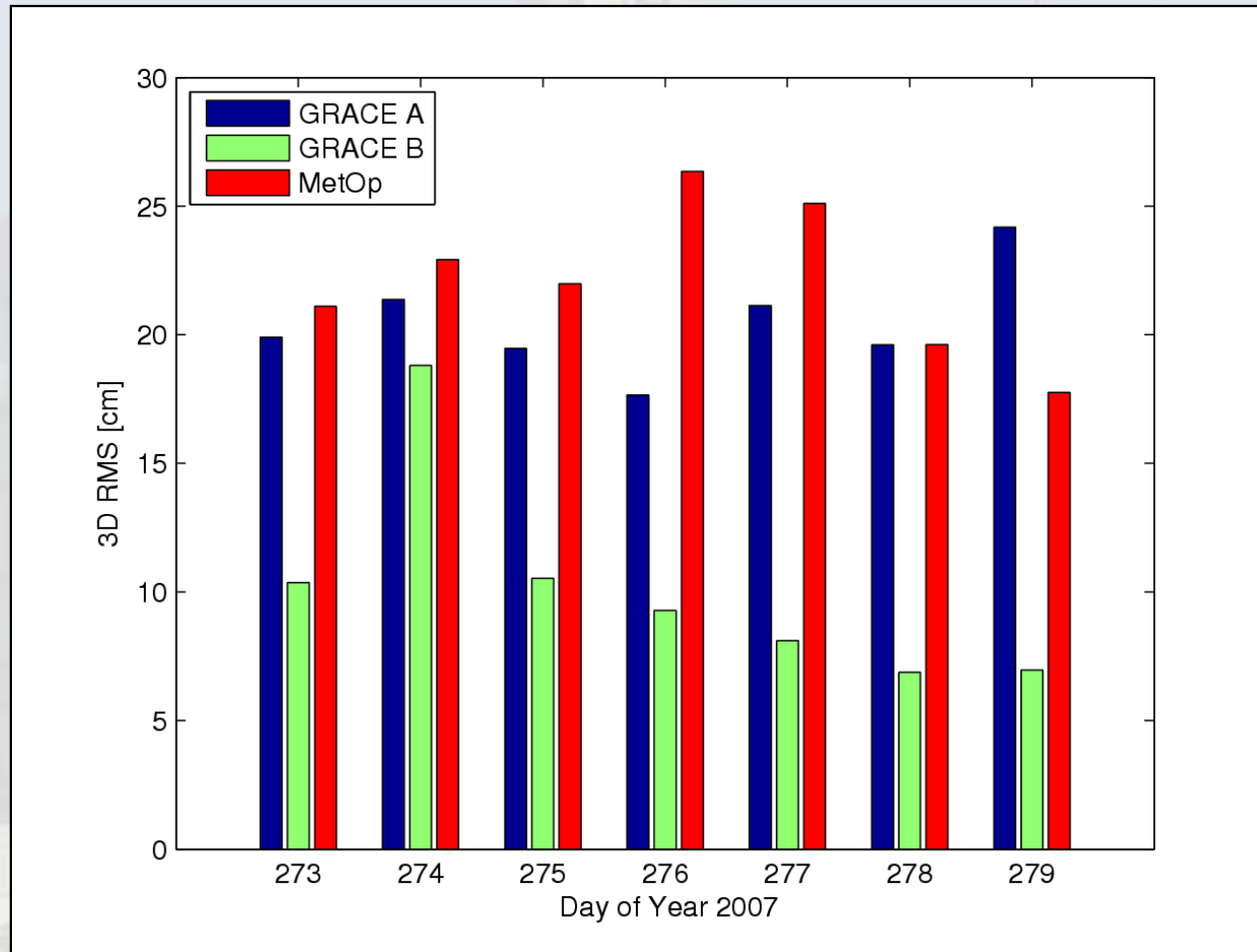
C/A-code noise is very  
low ( $\sim 10$  cm)

**MetOp:**

Observation noise is  
 $\sim 3$  times larger than  
for GRACE B

Pre-processing based on DF data (L1/L2 and C1/P2), 10 sec

# 1. Handling ionosphere: Solution C - SIPs



Mean 3D RMS:

20.5 cm

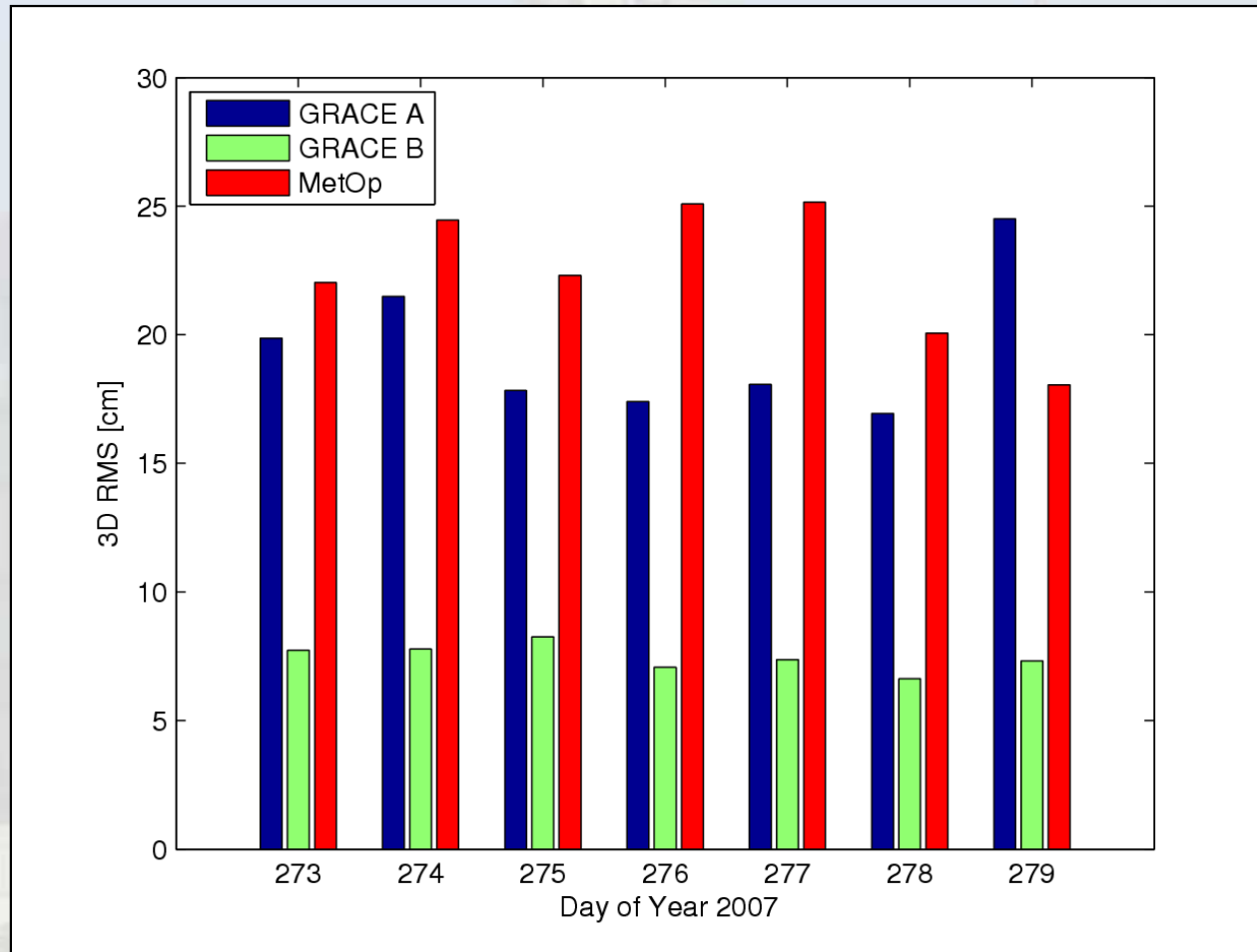
10.1 cm

22.1 cm

SIP solution (C) is slightly worse (5-10%) compared to GRAPHIC solution (B)

Pre-processing based on DF data (L1/L2 and C1/P2), 10 sec

## 2. Pre-processing: Solution C - SIPs



Mean 3D RMS:

19.4 cm

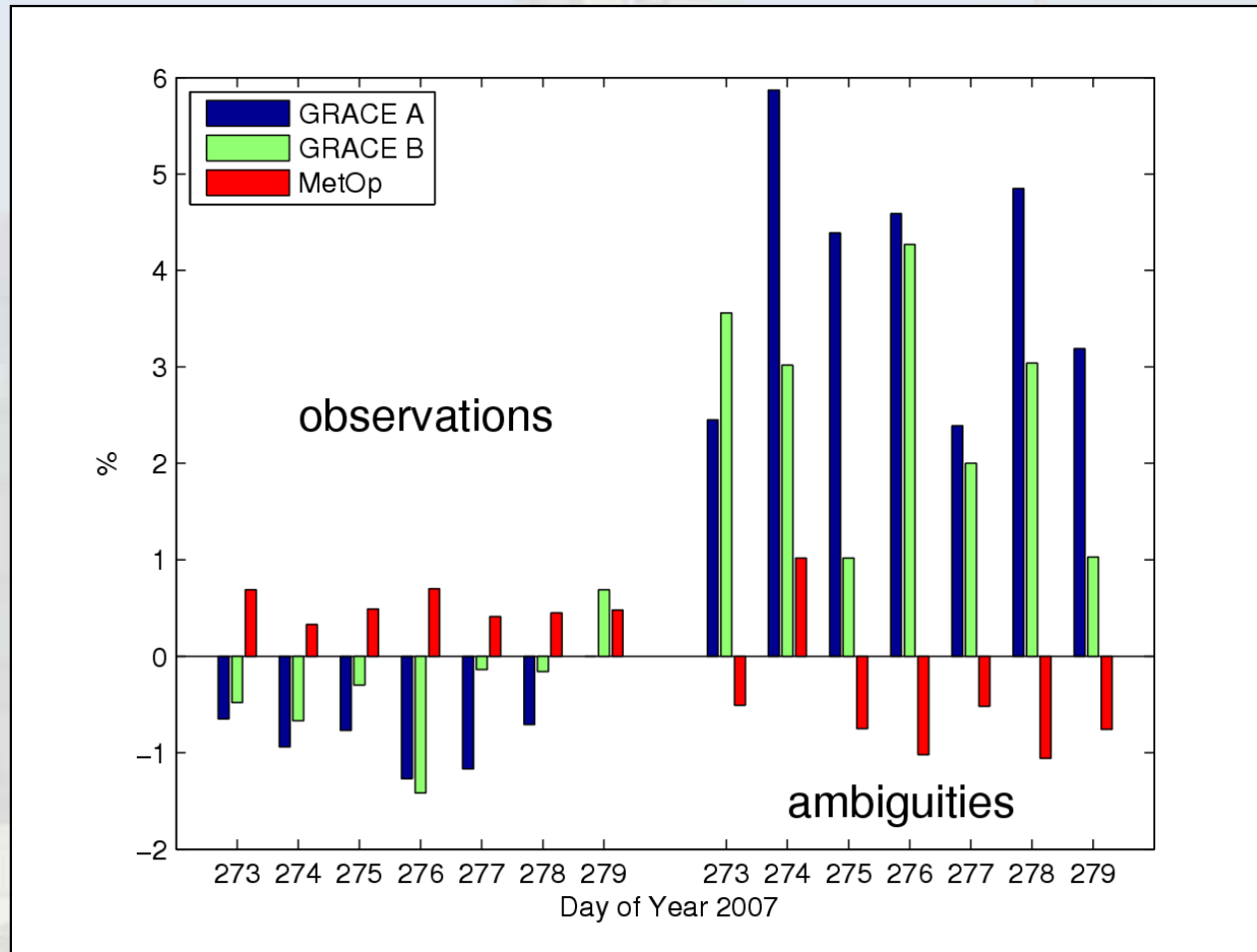
7.5 cm !!

22.5 cm

Pure SF results are of comparable quality  
=> pre-processing also works with SF data

Pre-processing based on SF data (L1 and C1), 10 sec

## 2. Pre-processing: Quality



Percentage relative to DF reference solution

### GRACE A/B:

- less observations
- more ambiguities

### MetOp:

- more observations
- less ambiguities

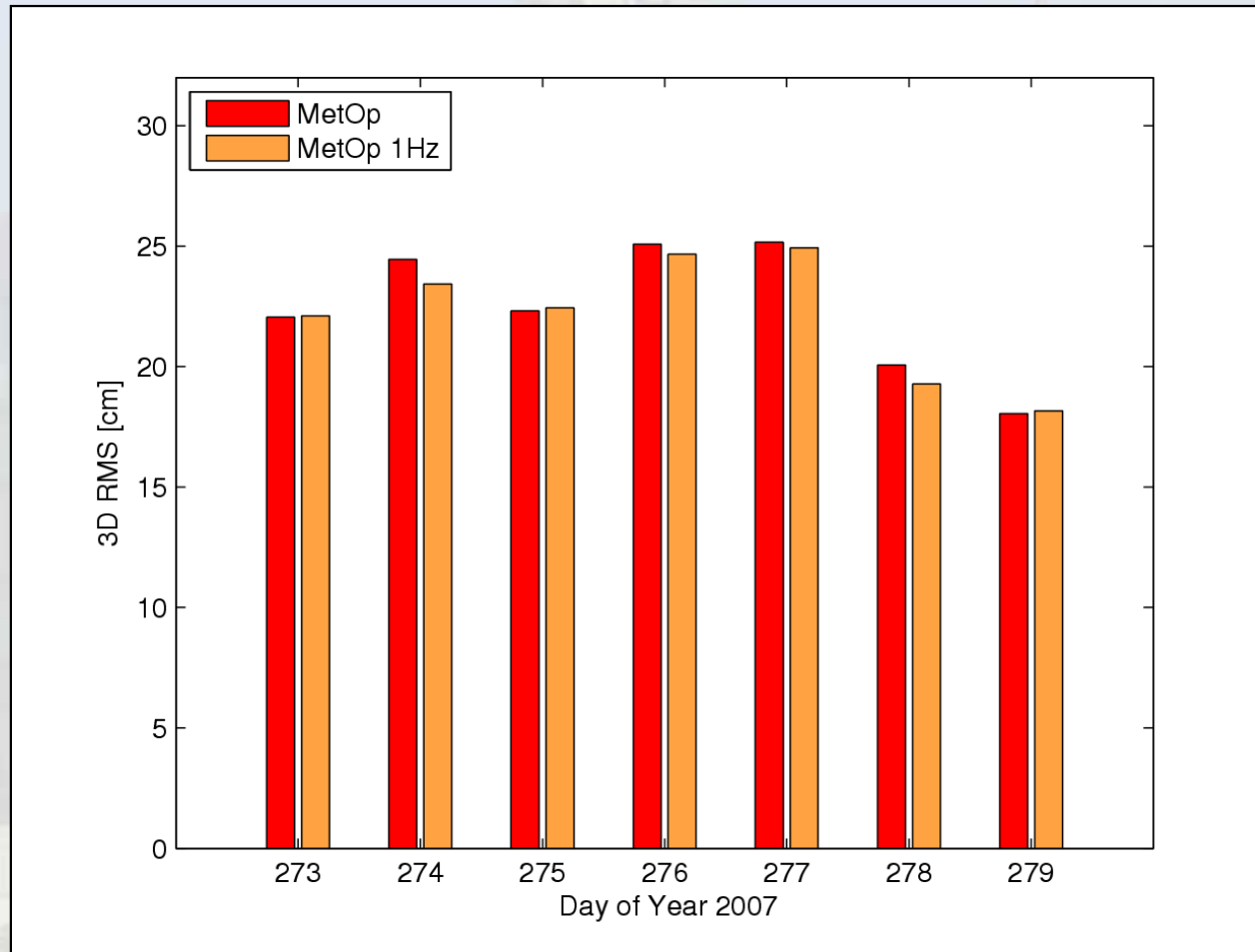
Pre-processing:  
remaining ionospheric  
effect in observations



cycle slip detection

➤ phase ambiguity  
setting

### 3. Higher sampling rate



Mean 3D RMS:

22.5 cm

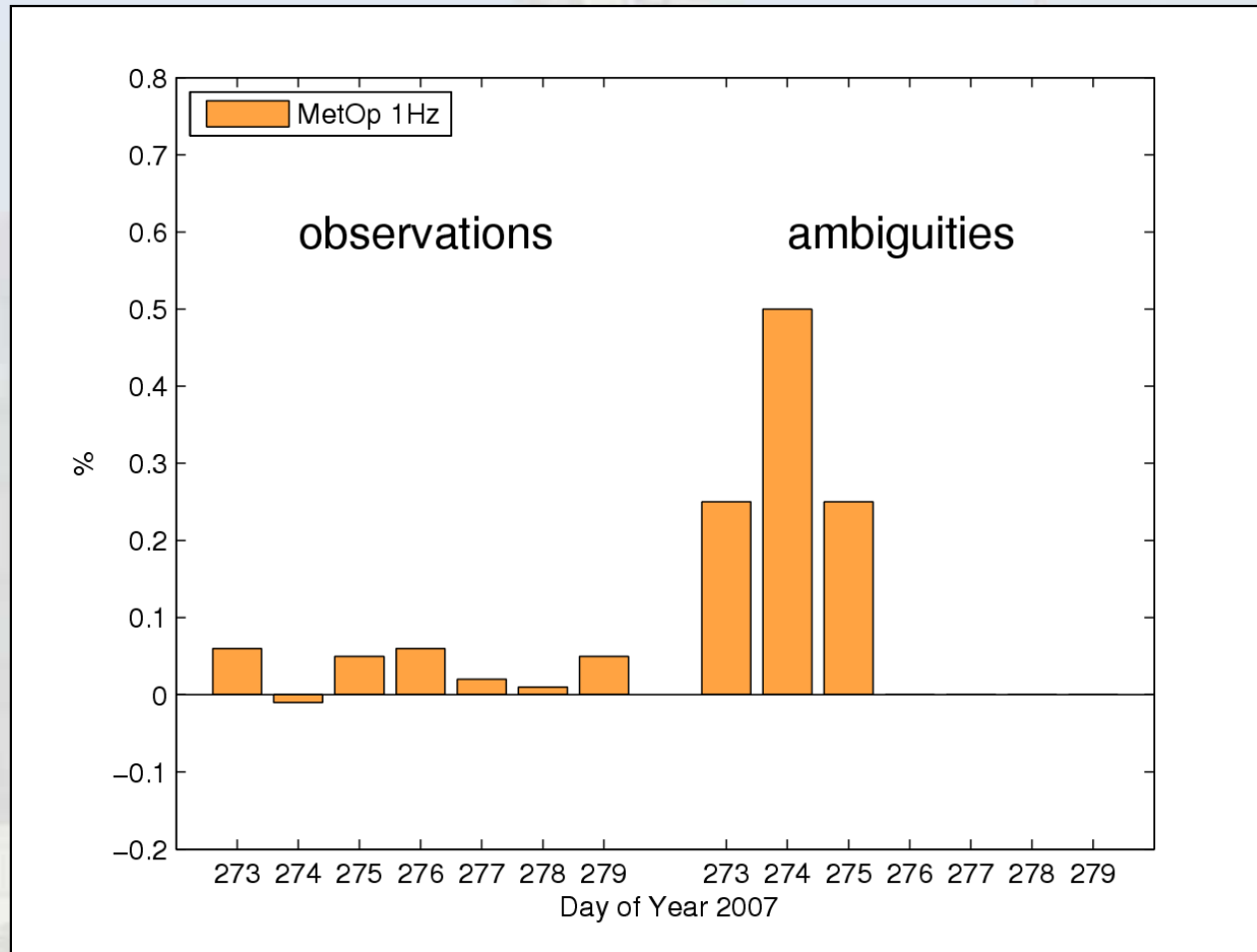
22.1 cm

The orbital altitude from **MetOp** is already too high to profit from the higher sampling rate for the pre-processing.

Pre-processing based on SF data (L1 and C1), 10 sec/1 sec



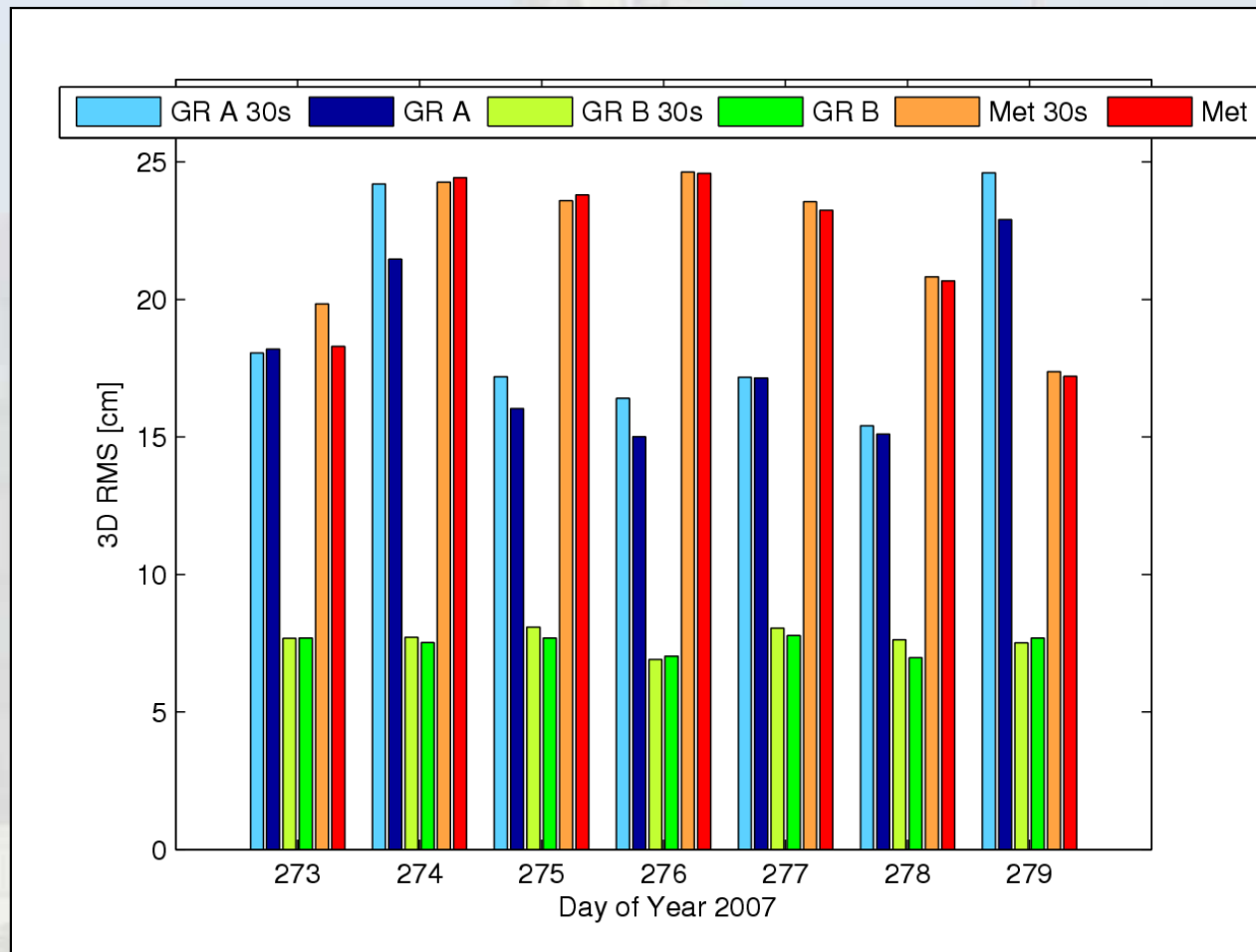
### 3. Quality, higher sampling rate



The orbital altitude from **MetOp** is already too high to profit from the higher sampling rate for the pre-processing.

Percentage relative to SF 10 sec solution

### 3. Lower sampling rate



Mean 3D RMS:

19.0 cm

18.0 cm

7.7 cm

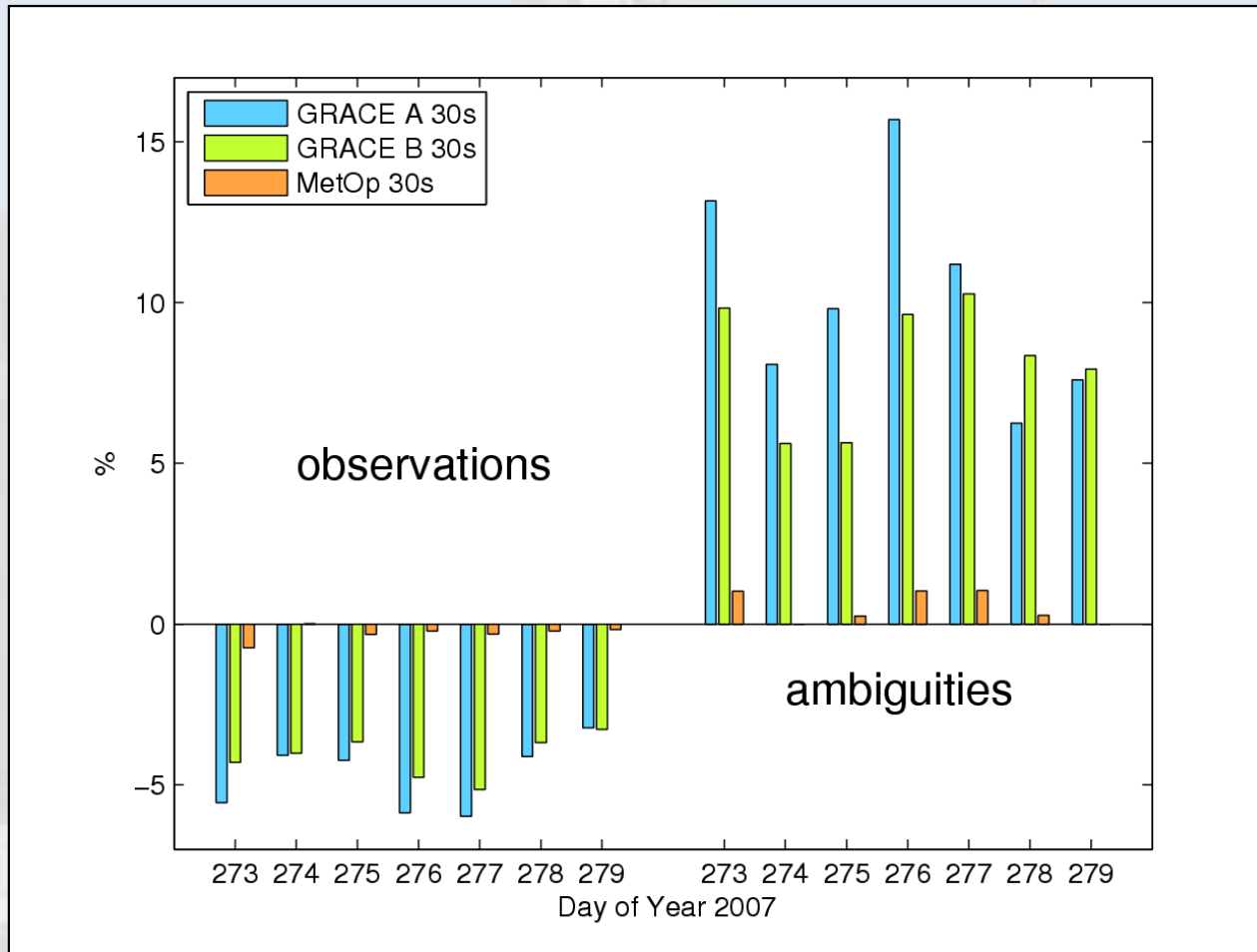
7.5 cm

22.0 cm

21.8 cm

Pre-processing based on SF data (L1 and C1), 30 sec/10 sec,  
orbit solutions with 30 sec sampling

### 3. Quality, lower sampling rate



#### GRACE A/B:

- **less** observations
- **more** ambiguities

#### MetOp:

- no significant differences

Pre-processing with lower sampling rate is much more difficult for lower satellites (ionosphere)

Percentage relative to 10 sec SF solution

# Conclusion

*Which orbit accuracies are possible with GPS SF OD?*

**=> 1 - 2 dm 3d RMS; < 1 dm, if C/A code is good.**

1. Which is the best solution/possibility to handle the ionospheric effect in the observations?

**=> L1 and C1 observations, GRAPHIC (B) or SIP (C).**

2. How good does the pre-processing work?

**=> Comparable quality as the DF pre-processing.**

3. Is the orbital height and/or the data sampling rate an important quality factor?

**=> Yes, the lower the satellite the better a higher sampling rate for a good pre-processing.**

# End: Orbit differences

